



On abstract indefinite concave–convex problems and applications to quasilinear elliptic equations

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Abstract. In this work we study the existence of critical points of an abstract C^1 functional J defined in a reflexive Banach space X . This functional is of the form

$$J(u) = \frac{1}{p}E(u) - \frac{1}{r}A(u) - \frac{1}{q}B(u),$$

with E, A, B positive-homogeneous **indefinite** functional of degree p, q, r respectively and $1 < p < q < r$. The critical points are found by minimization along several subsets of the Nehari manifold associated to J . We apply these results to various quasilinear elliptic problems, as for instance, the following p -laplacian concave–convex problem with Steklov boundary conditions on a bounded regular domain

$$\begin{cases} -\Delta_p u + V(x)u^{p-1} = 0 & \text{in } \Omega; \\ |\nabla u|^{p-2} \frac{\partial u}{\partial \nu} = \lambda a(x)u^{r-1} + b(x)u^{q-1} & \text{on } \partial\Omega; \\ u > 0 & \text{in } \Omega, \end{cases}$$

with given functions a, b, V possibly indefinite and $1 < r < p < q$. We also apply our abstract result for a concave–convex quasilinear problem associated to the p -bilaplacian.

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1. Introduction

After the celebrated paper of Ambrosetti-Brézis-Cerami [1] on the solvability of the elliptic problem

$$\begin{cases} -\Delta u = f_\lambda(u) & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega, \\ u > 0 & \text{in } \Omega, \end{cases}$$

for $f_\lambda(u) = \lambda u^{r-1} + u^{q-1}$ and $1 < r < 2 < q$, there have been a huge amount of research on this type of equations and the effects on multiplicity of the concave ($1 < r < 2$)-convex ($2 < q$) nonlinearity. In [3–5] the authors studied the previous equation with a concave–convex forcing term $f_\lambda(u) = \lambda a(x)u^{r-1} + b(x)u^{q-1}$ with changing-sign weights $a(x), b(x)$ by using the so called *Nehari manifold and the fibering map* associated to the problem. This approach has proved to be very useful to deal with this type of problem and have become a subject of research on its own. The results of [1] were partially generalized to the p -laplacian operator under Dirichlet boundary conditions in [2, 8, 11, 12, 21]. Soon later, other boundary conditions have been considered, as for instance in [17]. Simultaneously some attention has been accorded to quasilinear problems that *are non coercive*. The first work in this direction was the study of the spectrum of the operator $-\Delta_p u + V(x)|u|^{p-2}u$ with Dirichlet boundary conditions and V an indefinite bounded weight, see [7]. In [16] the author studied the concave–convex problem

$$\begin{cases} -\Delta_p u + V(x)u^{p-1} = \lambda a(x)u^{r-1} + b(x)u^{q-1} & \text{in } \Omega; \\ u = 0 & \text{on } \partial\Omega; \\ u > 0 & \text{in } \Omega, \end{cases}$$

by minimization on the Nehari set and obtained, under various “coerciveness” conditions related to V , a and b , the existence of up to *four solutions*: two solutions satisfying the condition $E_V(u) > 0$ with

$$E_V(u) := \int_\Omega (|\nabla u|^p + V(x)|u|^p) \, dx,$$

and two more solutions satisfying $E_V(u) < 0$.

Our goal in this work is to generalize the results of [16] for the same quasilinear operator, say $-\Delta_p u + V(x)|u|^{p-2}u$, but with different boundary conditions. Precisely, let Ω be a bounded smooth domain of class $C^{2,\alpha}$ ($0 < \alpha < 1$) with outward unit normal ν on the boundary $\partial\Omega$ and $\Delta_p u := \operatorname{div}(|\nabla u|^{p-2}\nabla u)$ is the well known p -laplacian operator. The functions $V \in L^\infty(\Omega)$ and $(a, b) \in (C^s(\partial\Omega))^2$, for some $s \in (0, 1)$, are allowed to change sign. The real number λ is a positive parameter. We will ask the exponents r, q to satisfy $1 < r < p < q < p_*$ where $p_* = \frac{p(N-1)}{(N-p)^+}$ is the critical exponent for the trace operator $W^{1,p}(\Omega) \rightarrow L^s(\partial\Omega, d\rho)$, and ρ denotes the restriction to $\partial\Omega$ of the $(N - 1)$ -Hausdorff measure, which coincides with the usual Lebesgue surface measure as $\partial\Omega$ is regular enough. We will consider the following quasilinear elliptic

Problem I:

$$\begin{cases} -\Delta_p u + V(x)u^{p-1} = 0 & \text{in } \Omega; \\ |\nabla u|^{p-2} \frac{\partial u}{\partial \nu} = \lambda a(x)u^{r-1} + b(x)u^{q-1} & \text{on } \partial\Omega; \\ u > 0 \text{ in } \Omega, \end{cases} \quad (1.1)$$

and **Problem II:**

$$\begin{cases} -\Delta_p u + V(x)u^{p-1} = \lambda a(x)u^{r-1} & \text{in } \Omega; \\ |\nabla u|^{p-2} \frac{\partial u}{\partial \nu} = b(x)u^{q-1} & \text{on } \partial\Omega; \\ u > 0 \text{ in } \Omega. \end{cases} \quad (1.2)$$

The search of solutions for these quasilinear problems can be stated in an **abstract form** as the search of critical points of a functional J defined on a Banach space X , which will take the form

$$J(u) = \frac{1}{p}E(u) - \frac{1}{r}A(u) - \frac{1}{q}B(u), \quad (1.3)$$

where E, A, B are possibly indefinite but positive-homogeneous functional of degree p, r, q respectively, with $1 < r < p < q$. We will prove several existence and multiplicity results on critical points of J by minimizing J along several subsets of the **Nehari** manifold

$$\mathcal{N} = \{u \in X \setminus \{0\}; \langle J'(u), u \rangle = 0\}$$

associated to J . These existence results for a general functional E, A, B and X can be applied in many cases, as for instance for the p -bilaplacian operator with Navier boundary conditions, that is the following **Problem III:**

$$\begin{cases} \Delta_p^2 u - c|u|^{p-2}u = \lambda a(x)|u|^{r-2}u + b(x)u^{q-2}u & \text{in } \Omega; \\ u = \Delta u = 0 & \text{on } \partial\Omega, \end{cases} \quad (1.4)$$

with $c \in \mathbb{R}$. The p -bilaplacian operator is defined as $\Delta_p^2 u := \Delta(|\Delta u|^{p-2} \Delta u)$ and it has received recently some attention. In the case $p = 2$ the authors in [22] generalize the Ambrosetti–Brézis–Cerami problem in the case $c = 0$ (coercive case), indefinite weight a and non-negative weight b . See also [15] for similar results in \mathbb{R}^N or [13] for Dirichlet boundary conditions ($u = \nabla u = 0$) and $p \neq 2$.

This paper is organized as follows. In Sect. 2 we describe the Nehari set, the fibering map and the different “sign-subsets” of the Nehari set that will be used to find critical points of the C^1 functional J which is defined in (1.3). In Sects. 3 and 4 we prove four different critical points theorems of the functional J in the Nehari set, c.f. Theorems 3.3, 3.4, 4.1 and 4.2. The hypothesis needed to apply these general theorems concern the coerciveness of E along the sign-subsets of the Nehari set described in Sect. 2. In Sect. 5 we present various conditions in terms of eigenvalues-like numbers that will imply the required coerciveness and then we prove some existence results (see Theorems 5.1 and 5.7). In Sect. 6 we apply the theorem of the previous section to state some existence and multiplicity results for problems I, II and III.

2. The Nehari set for a concave–convex functional

Let $(X, \|\cdot\|)$ be a reflexive Banach space and $E, A, B \in C^1(X, \mathbb{R})$. Let us assume that for some $1 < r < p < q$ it holds

$$E(tu) = t^p E(u), \quad A(tu) = t^r A(u), \quad B(tu) = t^q B(u), \quad \forall (t, u) \in \mathbb{R}^+ \times X. \tag{2.1}$$

The following hypothesis will also be assumed:

(H1) $\forall (u_n)_{n \in \mathbb{N}}, u_n \in X$, if $u_n \rightharpoonup u$ for some $u \in X$ then there exists a subsequence u_{n_k} such that

$$A(u_{n_k}) \rightarrow A(u) \text{ and } B(u_{n_k}) \rightarrow B(u).$$

(H2) E is bounded on bounded sets (i.e. $\sup_{u \in X, \|u\|=1} |E(u)| < \infty$) and it is weakly lower semi-continuous.

(H3) $\forall (u_n)_{n \in \mathbb{N}}, u_n \in X$, if $u_n \rightharpoonup u$ for some $u \in X$ and $E(u_n) \rightarrow E(u)$ then $u_n \rightarrow u$.

By " \rightharpoonup " we denote the weak convergence in X . Let us consider the functional J defined as

$$J(u) = \frac{1}{p} E(u) - \frac{1}{r} A(u) - \frac{1}{q} B(u)$$

and look for solutions of the problem $J'(u) = 0$. Since J may be unbounded from below on the set $\{u \in X ; B(u) > 0\}$, it is useful to consider the functional J restricted to the so called **Nehari set**

$$\mathcal{N} := \{u \in X \setminus \{0\} ; N(u) := \langle J'(u), u \rangle = 0\},$$

where $\langle \cdot, \cdot \rangle$ is the usual duality map defined on $X' \times X$. Thus $u \in \mathcal{N}$ if and only if $u \neq 0$ and

$$E(u) = A(u) + B(u).$$

Let us introduce the **fibering maps** associated to J . For $u \in X \setminus \{0\}$, we define the function

$$\begin{aligned} J_u : (0, \infty) &\longrightarrow \mathbb{R} \\ t &\longmapsto J_u(t) := J(tu). \end{aligned}$$

Consequently $u \in \mathcal{N}$ if and only if $J'_u(1) = 0$ or yet, $tu \in \mathcal{N}$ (with $t > 0$) if and only if $J'_u(t) = 0$. The notation J'_u, J''_u stands here for $\frac{dJ_u}{dt}, \frac{d^2J_u}{dt^2}$ resp. Furthermore, since $J'_u(u) = 0$ for $u \in \mathcal{N}$ we can write

$$\begin{aligned} J''_u(1) &= (p - q)E(u) - (r - q)A(u) \\ &= (p - r)E(u) - (q - r)B(u). \end{aligned} \tag{2.2}$$

It is standard to split \mathcal{N} into three sets that, roughly speaking, correspond to local minima, local maxima and inflexion points of J_u :

$$\begin{aligned} \mathcal{N}^+ &:= \left\{ u \in X ; J'_u(1) = 0, J''_u(1) > 0 \right\}, \\ \mathcal{N}^- &:= \left\{ u \in X ; J'_u(1) = 0, J''_u(1) < 0 \right\}, \\ \mathcal{N}_0 &:= \left\{ u \in X ; J'_u(1) = 0, J''_u(1) = 0 \right\}. \end{aligned}$$

We also introduce the following “sign-subsets”:

$$\begin{aligned} \mathcal{A}^\pm &:= \{u \in X; A(u) \geq 0\}, \quad \mathcal{A}_0 = \{u \in X; A(u) = 0\}, \\ \mathcal{B}^\pm &:= \{u \in X; B(u) \geq 0\}, \quad \mathcal{B}_0 = \{u \in X; B(u) = 0\}, \\ \mathcal{E}^\pm &:= \{u \in X; E(u) \geq 0\}, \quad \mathcal{E}_0 = \{u \in X; E(u) = 0\}. \end{aligned}$$

Finally we denote $\mathcal{A}_0^\pm = \mathcal{A}^\pm \cup \mathcal{A}_0$ and similarly for \mathcal{B}_0^\pm and \mathcal{E}_0^\pm . We stress here that, without further assumptions on E, A, B , the previous sets can be void.

Next we state the following property of \mathcal{N} that follows straight from hypothesis **(H1)**–**(H3)**.

Lemma 2.1. *Let u_n be a sequence in \mathcal{N} such that $u_n \rightarrow 0$. Then $u_n \rightarrow 0$.*

Let us give a result on the boundedness of \mathcal{N} . We recall that a subset C of X is called a *cone* if $tx \in C, \forall (t, x) \in \mathbb{R}^+ \times C$.

Lemma 2.2. *Let $C \subset X$ be weakly closed cone such that*

$$(C \cap \mathcal{B}_0) \setminus \{0\} \subset \mathcal{E}^+. \tag{2.3}$$

Then

- (i) *the set $\mathcal{N}^+ \cap C$ is bounded;*
- (ii) *if $\sup_{C \cap \mathcal{N}} J(u) < \infty$ then $\mathcal{N} \cap C$ is bounded.*

Proof. (i) Assume by contradiction that there is an unbounded sequence $u_n \in \mathcal{N}^+ \cap C$. Take $v_n = \frac{u_n}{\|u_n\|} \in C$ and $v_0 \in C$ such that $v_n \rightharpoonup v_0$. From the fact that $u_n \in \mathcal{N}$ we have

$$\frac{E(v_n)}{\|u_n\|^{q-p}} = \frac{A(v_n)}{\|u_n\|^{q-r}} + B(v_n)$$

and passing to the limit we conclude that $B(v_0) = 0$. We have used here that E is bounded on bounded sets [i.e. **(H2)**]. From the fact that $u_n \in \mathcal{N}^+$ we have

$$E(v_n) < \frac{q-r}{q-p} \frac{A(v_n)}{\|u_n\|^{p-r}}$$

and passing to the limit it comes that $E(v_0) \leq 0$. The possibility of $v_0 = 0$ is ruled out by the fact that, in that case, $0 = E(v_0) = \liminf_{n \rightarrow \infty} E(v_n)$ and therefore, by **(H3)**, we will have $v_n \rightarrow v_0 = 0$. This is a contradiction with the property $\|v_n\| = 1$. Thus $v_0 \neq 0$ and we get a contradiction with the hypothesis **(2.3)** of the lemma.

(ii) Assume that $u_n \in \mathcal{N} \cap \mathcal{C}$ is a sequence satisfying $\|u_n\| \rightarrow +\infty$ and denote $v_n = \frac{u_n}{\|u_n\|}$. Since the sequence v_n is bounded, there exists $v_0 \in X$ and a subsequence v_{n_k} such that $v_{n_k} \rightharpoonup v_0$. From the fact that $u_{n_k} \in \mathcal{N}$ we have, as previously, $0 = B(v_0)$. On the other hand

$$\frac{J(u_{n_k})}{\|u_{n_k}\|^p} = \left(\frac{1}{p} - \frac{1}{q}\right) E(v_{n_k}) - \left(\frac{1}{r} - \frac{1}{q}\right) \frac{A(v_{n_k})}{\|u_{n_k}\|^{p-r}}$$

therefore passing to the limit we get

$$E(v_0) \leq \liminf_{k \rightarrow +\infty} E(v_{n_k}) \leq 0$$

because $J(u_n)$ is uniformly bounded from above. If $v_0 = 0$ hence $E(v_0) = 0 = \liminf_{k \rightarrow +\infty} E(v_{n_k})$ and, from hypothesis **(H3)**, $v_{n_k} \rightarrow v_0 = 0$. This is impossible because $\|v_{n_k}\| = 1$ for all k . Thus $v_0 \neq 0$ and we get again a contradiction with the hypothesis (2.3) of the lemma. \square

We also have the following property:

Lemma 2.3. *Let $\mathcal{C} \subset X$ be weakly closed cone and assume that*

$$\mathcal{C} \cap \mathcal{A}_0 \setminus \{0\} \subset \mathcal{E}^+. \tag{2.4}$$

Then $\mathcal{N}^- \cap \mathcal{C}$ has no sequence $u_n \rightarrow 0$.

Proof. Assume by contradiction that there is a sequence $u_n \in \mathcal{N}^- \cap \mathcal{C}$ such that $u_n \rightarrow 0$ in X . From the fact that $u_n \in \mathcal{N}$ we have $0 = E(0) \leq \liminf E(u_n) = \liminf A(u_n) + B(u_n)$ so $u_n \rightarrow 0$ on X . Take $z_n := \frac{u_n}{\|u_n\|} \in \mathcal{C}$ and assume that for some $z_0 \in X$ we have $z_n \rightharpoonup z_0$, $A(z_n) \rightarrow A(z_0)$ and $B(z_n) \rightarrow B(z_0)$. By using that $u_n \in \mathcal{N}$ we have

$$A(z_n) = E(z_n)\|u_n\|^{p-r} - B(z_n)\|u_n\|^{q-r}$$

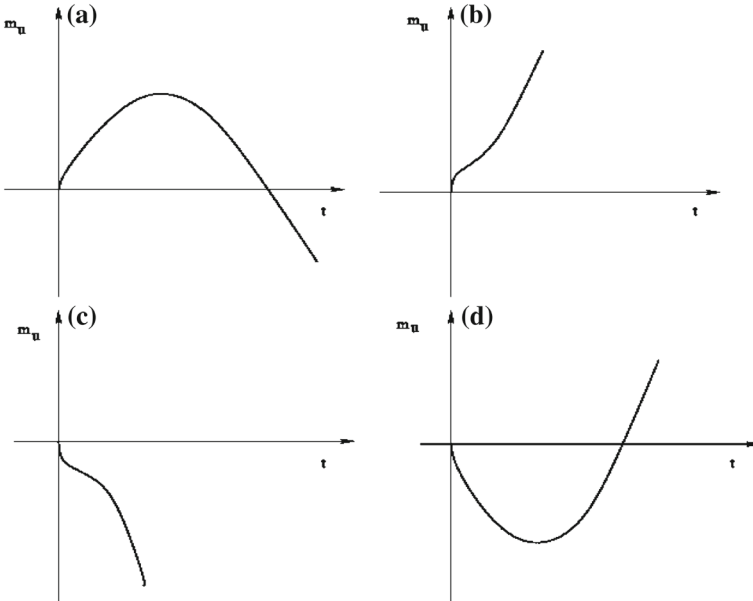
and passing to the limit it comes $A(z_0) = 0$. Besides by using that $u_n \in \mathcal{N}^-$ and (2.2) we have

$$E(z_n) \leq \frac{q-r}{p-r} B(z_n)\|u_n\|^{q-p},$$

and passing to the limit

$$E(z_0) \leq \liminf E(z_n) \leq 0.$$

Notice that the possibility $z_0 = 0$ is excluded because, in that case, we would have $0 = E(z_0) = \liminf E(z_n)$ which will imply that $z_n \rightarrow z_0 = 0$, a contradiction with the fact that $\|z_n\| = 1$. Thus we have proved that $z_0 \in \mathcal{C} \cap \mathcal{A}_0 \setminus \{0\}$. Then from the hypothesis (2.4) of this lemma it comes that $E(z_0) > 0$, a contradiction. \square

FIGURE 1. Possible forms of m_u

2.1. The fibering map

Let us give a complete description of the behaviour of J_u according to the sign of $A(u)$, $B(u)$ and $E(u)$. Let us write

$$J'_u(t) = t^{p-1}E(u) - t^{r-1}A(u) - t^{q-1}B(u) = t^{r-1}[m_u(t) - A(u)],$$

where

$$m_u(t) := t^{p-r}E(u) - t^{q-r}B(u). \quad (2.5)$$

Clearly, for $t > 0$, $tu \in \mathcal{N}$ if and only if t is a solution of the equation

$$m_u(t) = A(u). \quad (2.6)$$

If for $u \in X \setminus \{0\}$ and $t > 0$ one has that $J'_u(t) = 0$ then $J''_u(t) = t^{r-1}m'_u(t)$. Consequently $tu \in \mathcal{N}^+$ if and only if $m'_u(t) > 0$ (similar results for \mathcal{N}^- and \mathcal{N}_0). In order to study the resolvability of (2.6) let us describe the variation of the function $t \mapsto m_u(t)$ for any $u \notin \mathcal{E}_0 \cap \mathcal{B}_0$. Four possible pictures of the graph of m_u can be drawn:

- Case I** : $E(u) > 0$ and $B(u) > 0$ in Fig. 1a;
- Case II** : $E(u) \geq 0$ and $B(u) \leq 0$ in Fig. 1b;
- Case III** : $E(u) \leq 0$ and $B(u) \geq 0$ in Fig. 1c;
- Case IV** : $E(u) < 0$ and $B(u) < 0$ in Fig. 1d.

We shall now describe the nature of the fibering maps for all possible signs of $A(u)$, $B(u)$ and $E(u)$. The following behaviour of the function J_u follows from the previous description of the function m_u . As above, we will assume that $u \notin \mathcal{E}_0 \cap \mathcal{B}_0$.

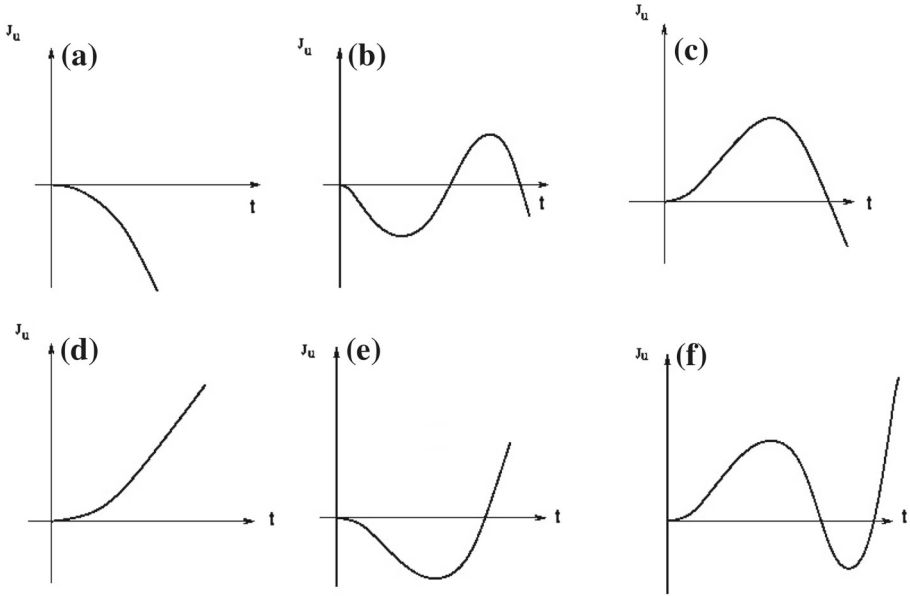


FIGURE 2. Possible forms of J_u

Case 1 : $E(u) > 0$ and $B(u) > 0$.

In this case the function m_u has graph as shown in Fig. 1a.

Case 1.1 : If $A(u) > 0$ and $A(u) < \max_{t>0} m_u(t)$ then it is clear that there are exactly two solutions $0 < t_1(u) < t_2(u)$ of (2.6) with $m'_u(t_2(u)) < 0 < m'_u(t_1(u))$. Thus there are exactly two multiples of u lying in \mathcal{N} , namely $t_1(u)u \in \mathcal{N}^+$ and $t_2(u)u \in \mathcal{N}^-$. It follows that J_u has exactly two critical points, a local minimum at $t_1(u)$ and a local maximum at $t_2(u)$. Moreover J_u is decreasing in $(0, t_1(u))$ and in $(t_2(u), \infty)$, increasing in (t_1, t_2) , see Fig. 2b.

Case 1.2 : If $A(u) \leq 0$. Then using the graph of m_u in Fig. 1a, we deduce that there exists one positive solution of (2.6). Consequently J_u has graph as shown in Fig. 2c and there is a unique value $t(u) > 0$ such that $t(u)u \in \mathcal{N}$. Moreover $m'_u(t(u)) < 0$, so $t(u)u \in \mathcal{N}^-$ and the fibering maps J_u has a unique critical point which is a local maximum.

Case 2 : $E(u) \geq 0$ and $B(u) \leq 0$.

In this case the function m_u is an increasing function of t (see Fig. 1b).

Case 2.1 : If $A(u) > 0$, then m_u has a graph as in Fig. 1b and J_u has a graph as shown in Fig. 2e. It is clear that there is exactly one solution of (2.6), i.e. there is a unique $t(u) > 0$ such that $t(u)u \in \mathcal{N}$. Moreover $m'_u(t(u)) > 0$ (since m_u is an increasing function of t) and so $t(u)u \in$

\mathcal{N}^+ . Thus the fibering map J_u has a unique critical point which is a local minimum, as shown in Fig. 2e.

Case 2.2 : If $A(u) \leq 0$ then the function J_u is increasing functions of t and so has graph as shown in Fig. 2d. Consequently (2.6) has no solution, for all t and thus no multiple of u lies in \mathcal{N} .

Case 3 : $E(u) \leq 0$ and $B(u) \geq 0$.

In this case the function m_u is a decreasing function of t and has graph as shown in Fig. 1c.

Case 3.1 : If $A(u) < 0$ then (2.6) has a unique solution. Since J_u must have graph as shown in Fig. 2c, we conclude again that there is a unique $t(u) > 0$ such that $t(u)u \in \mathcal{N}$ and since $m'_u(t(u)) < 0$ in this case, we deduce that $t(u)u \in \mathcal{N}^-$. Hence the fibering map J_u has a unique critical point which is a local maximum.

Case 3.2 : If $A(u) \geq 0$ then (2.6) has no solution. Moreover J_u is a decreasing function of t and has graph as shown in Fig. 2a. Thus in this case no multiple of u lies in \mathcal{N} .

Case 4 : $E(u) < 0$ and $B(u) < 0$.

In this case m_u has graph as shown in Fig. 1d.

Case 4.1 : If $A(u) < 0$ and $A(u) > \min_{t>0} m_u(t)$ then J_u has graph as shown in Fig. 2f. In this case there are exactly two solutions $t_1(u) < t_2(u)$ of (2.6) with $m'_u(t_1(u)) < 0 < m'_u(t_2(u))$. Thus there are exactly two multiples of u which belong to \mathcal{N} , namely $t_1(u) \in \mathcal{N}^-$ and $t_2(u) \in \mathcal{N}^+$. It follows that J_u has exactly two critical points, a local maximum at $t = t_1(u)$ and a local minimum at $t = t_2(u)$. Furthermore J_u is increasing in $(0, t_1)$, decreasing in (t_1, t_2) and increasing in (t_2, ∞) , as in Fig. 2f.

Case 4.2 : If $A(u) \geq 0$ then (2.6) has a unique solution and J_u has graph as shown in Fig. 2e. Thus there is a unique value $t(u) > 0$ such that $t(u)u \in \mathcal{N}$. Since $m'_u(t(u)) > 0$, we deduce that $t(u)u \in \mathcal{N}^+$ and consequently J_u has a unique critical point which is a local minimum as shown in Fig. 2e.

It comes out from this calculation that

Proposition 2.4. (i) *If either $\mathcal{A}^+ \cap \mathcal{B}_0^- \cap \mathcal{E}^+ \neq \emptyset$ or*

$$\Lambda^+ := \{u \in \mathcal{A}^+ \cap \mathcal{B}^+ \cap \mathcal{E}^+ ; A(u) < \max_{t>0} m_u(t)\} \neq \emptyset$$

then $\mathcal{N}^+ \cap \mathcal{E}^+ \neq \emptyset$.

(ii) *If either $\mathcal{A}_0^- \cap \mathcal{B}^+ \cap \mathcal{E}^+ \neq \emptyset$ or $\Lambda^+ \neq \emptyset$ then $\mathcal{N}^- \cap \mathcal{E}^+ \neq \emptyset$.*

(iii) *If $\Lambda^- := \{u \in \mathcal{A}^- \cap \mathcal{B}^- \cap \mathcal{E}^- ; A(u) > \min_{t>0} m_u(t)\} \neq \emptyset$ then $\mathcal{N}^+ \cap \mathcal{A}^- \neq \emptyset$.*

(iv) *If $\Lambda^- \neq \emptyset$ then $\mathcal{N}^- \cap \mathcal{B}^- \neq \emptyset$.*

A simple calculation shows that the maximum of m_u in case I is

$$\max_{t>0} m_u(t) = \left(\frac{q-p}{q-r}\right) \left(\frac{p-r}{q-r}\right)^{\frac{p-r}{q-p}} \frac{E(u)^{\frac{q-r}{q-p}}}{B(u)^{\frac{p-r}{q-p}}}$$

and the minimum of m_u in case IV is

$$\min_{t>0} m_u(t) = - \left(\frac{q-p}{q-r} \right) \left(\frac{p-r}{q-r} \right)^{\frac{p-r}{q-p}} \frac{(-E(u))^{\frac{q-r}{q-p}}}{(-B(u))^{\frac{p-r}{q-p}}}.$$

The maximum (resp. the minimum) of m_u is achieved at the point

$$t_*(u) := \left(\frac{(p-r)E(u)}{(q-r)B(u)} \right)^{\frac{1}{q-p}}. \tag{2.7}$$

Let us denote

$$\lambda_*^+ := \inf_{u \in \mathcal{A}^+ \cap \mathcal{B}^+ \cap \mathcal{E}^+} \frac{\max_{t>0} m_u(t)}{A(u)} \geq 0 \tag{2.8}$$

in case I and

$$\lambda_*^- := \inf_{u \in \mathcal{A}^- \cap \mathcal{B}^- \cap \mathcal{E}^-} \frac{\min_{t>0} m_u(t)}{A(u)} \geq 0 \tag{2.9}$$

in case IV. From the previous discussion it follows trivially that:

Lemma 2.5. (i) If $\lambda_*^+ > 1$ then $\mathcal{N}_0 \cap \mathcal{E}^+ = \emptyset$. (ii) If $\lambda_*^- > 1$ then $\mathcal{N}_0 \cap \mathcal{E}^- = \emptyset$.

3. Local minimizers of J restricted to the Nehari set and to \mathcal{E}^+

Our purpose in this section is to prove that, under some suitable assumptions on $\mathcal{A}^\pm, \mathcal{B}^\pm$ and \mathcal{E}^\pm , the functional J is bounded below and achieves its infimum on some of the sign subsets of \mathcal{N} described in cases I to IV of Sect. 2. This will provide us critical points for J , as a consequence of the following well known result:

Lemma 3.1. Suppose that u is a local minimiser of J restricted to \mathcal{N} . If $u \notin \mathcal{N}^0$ then u is a critical point of J relative to X .

Proof. Since u is a minimiser of J on \mathcal{N} , there exists $\gamma \in \mathbb{R}$ (Lagrange multiplier) such that

$$J'(u) = \gamma N'(u). \tag{3.1}$$

Thus in particular we have

$$\langle J'(u), u \rangle = \gamma \langle N'(u), u \rangle,$$

which implies that $\gamma \langle N'(u), u \rangle = 0$ because $0 = N(u) = \langle J'(u), u \rangle$ (since $u \in \mathcal{N}$). Moreover

$$\begin{aligned} \langle N'(u), u \rangle &= pE(u) - rA(u) - qB(u) \\ &= (p-r)E(u) - (q-r)B(u) \\ &= J''_u(1). \end{aligned}$$

Consequently, if $u \notin \mathcal{N}^0$, that is $J''_u(1) \neq 0$, then $\gamma = 0$ and we conclude from (3.1) that u is a critical point of J . □

Let us rewrite the functional J for $u \in \mathcal{N}$ in two different forms:

$$\begin{aligned} J(u) &= \left(\frac{1}{p} - \frac{1}{r}\right) E(u) + \left(\frac{1}{r} - \frac{1}{q}\right) B(u) \\ &= \left(\frac{1}{p} - \frac{1}{q}\right) E(u) - \left(\frac{1}{r} - \frac{1}{q}\right) A(u). \end{aligned} \tag{3.2}$$

We then observe the following

Lemma 3.2. (a) $J(u) > 0$ for all $u \in (\mathcal{N}^- \cap \mathcal{A}_0^-) \cup (\mathcal{N}^- \cap \mathcal{B}_0^+) \cup (\mathcal{N}^- \cap \mathcal{E}_0^-)$;
 (b) $J(u) < 0$ for all $u \in (\mathcal{N}^+ \cap \mathcal{A}_0^+) \cup (\mathcal{N}^+ \cap \mathcal{B}_0^-) \cup (\mathcal{N}^+ \cap \mathcal{E}_0^+)$.

Proof. From (2.2) we deduce the following inequalities

(a) If $u \in \mathcal{N}^-$ then

$$\frac{q-r}{q-p} A(u) < E(u) < \frac{q-r}{p-r} B(u). \tag{3.3}$$

Hence

$$J(u) > \max \left\{ \frac{(q-r)(r-p)}{prq} A(u), \frac{(q-p)(r-p)}{pqr} E(u), \frac{(q-p)(q-r)}{pqr} B(u) \right\},$$

(b) Similarly, if $u \in \mathcal{N}^+$ then

$$\frac{q-r}{p-r} B(u) < E(u) < \frac{q-r}{q-p} A(u). \tag{3.4}$$

Hence

$$J(u) < \min \left\{ \frac{(q-r)(r-p)}{pqr} A(u), \frac{(q-p)(r-p)}{pqr} E(u), \frac{(q-p)(q-r)}{pqr} B(u) \right\}.$$

□

3.1. Minimizing J along \mathcal{N}^+

A first critical point of J can be found on $\mathcal{N}^+ \cap \mathcal{E}^+$, provided this set is not empty and some "coerciveness" conditions:

Theorem 3.3. Assume that $\mathcal{E}^+ \cap \mathcal{N}^+ \neq \emptyset$, $\lambda_*^+ > 1$ and

(H4) $(\mathcal{A}_0^+ \cap \mathcal{B}_0) \setminus \{0\} \subset \mathcal{E}^+$,

(H5) $\mathcal{A}^+ \subset \mathcal{E}^+$.

Then the following local infimum

$$i := \inf_{u \in \mathcal{N}^+ \cap \mathcal{E}^+} J(u)$$

is achieved. Furthermore $i < 0$.

Proof. The fact that $i < 0$ readily follows from Lemma 3.2(b). First we prove that $\mathcal{N}^+ \cap \mathcal{E}^+$ is bounded. Indeed $\mathcal{N}^+ \cap \mathcal{E}^+ \subset \mathcal{N}^+ \cap \mathcal{A}^+$ because of inequality (3.4) and, since \mathcal{A}_0^+ is a weakly closed cone, we have

that the condition (2.3) of Lemma 2.2 corresponds to hypothesis (H4), thus we conclude that $\mathcal{N}^+ \cap \mathcal{E}^+$ is bounded. Notice that in particular we have that $i > -\infty$. To prove that the infimum i is achieved take a minimizing

sequence u_n . Since this sequence is bounded there exists some $u_0 \in X$ such that, up to subsequence, $u_n \rightharpoonup u_0$. By using (3.2) we can write

$$J(u_n) = \left(\frac{1}{p} - \frac{1}{q}\right) E(u_n) - \left(\frac{1}{r} - \frac{1}{q}\right) A(u_n) \geq -\left(\frac{1}{r} - \frac{1}{q}\right) A(u_n).$$

and letting $n \rightarrow +\infty$ we get $A(u_0) \geq -i\left(\frac{1}{r} - \frac{1}{q}\right)^{-1} > 0$. Then it comes then from (H5) that $E(u_0) > 0$. We claim that u_n converges strongly to u_0 in X . Assume by contradiction that $u_n \not\rightarrow u_0$. We discuss two alternatives :

Alt. 1. $B(u_0) > 0$. Using the previous classification of the fibering maps, the graph of J_{u_0} is as the one in Fig. 2b so there exist $0 < t_1(u_0) < t_2(u_0)$ such that $t_1(u_0)u_0 \in \mathcal{N}^+ \cap \mathcal{E}^+$, $t_2(u_0)u_0 \in \mathcal{N}^- \cap \mathcal{E}^+$, J_{u_0} is increasing between $t_1(u_0)$ and $t_2(u_0)$ and decreasing elsewhere. Since we are assuming that $u_n \not\rightarrow u_0$ hence $u_0 \notin \mathcal{N}$ and therefore $t_1(u_0) \neq 1$. Let us distinguish two cases: (a) $1 \leq t_2(u_0)$ and (b) $1 > t_2(u_0)$. In case (a) we have

$$J(t_1(u_0)u_0) = J_{u_0}(t_1(u_0)) \leq J_{u_0}(1) < \liminf J_{u_n}(1) = \lim J(u_n) = i. \tag{3.5}$$

Moreover Lemma 2.5 and hypothesis (H4) imply that $\mathcal{N}_0 = \{0\}$. Thus (3.5) leads to a contradiction because $t_1(u_0)u_0 \in \mathcal{N}^+ \cap \mathcal{E}^+$. In case (b) using that

$$0 = J'_{u_0}(t_2(u_0)) < \liminf J'_{u_n}(t_2(u_0))$$

we conclude that $J'_{u_n}(t_2(u_0)) > 0$ for n large. Since 1 is a local minimum of J_{u_n} and the graph of J_{u_n} looks like the one of Fig. 2b then it must be $1 < t_2(u_0)$, a contradiction.

Alt. 2. $B(u_0) \leq 0$. The graph of J_u is as the one in Fig. 2e so there exists $0 < t(u_0)$ such that $t(u_0)u_0 \in \mathcal{N}^+ \cap \mathcal{E}^+$ and J_{u_0} has a global minimum in $t(u_0)$. If $t(u_0) \geq 1$ again we have (3.5), a contradiction. If $t(u_0) < 1$ we use that

$$0 = J'_{u_0}(t(u_0)) < \liminf J'_{u_n}(t(u_0)),$$

so then $J'_{u_n}(1) > 0$ for n large, which is also impossible because $u_n \in \mathcal{N}$. \square

3.2. Minimizing J along \mathcal{N}^-

We now look for solutions of $J'(u) = 0$ in $\mathcal{N}^- \cap \mathcal{E}^+$.

Theorem 3.4. *Let us assume that $\mathcal{N}^- \cap \mathcal{E}^+ \neq \emptyset$, $\lambda_*^+ > 1$ and*

(H6) $\mathcal{B}_0^+ \setminus \{0\} \subset E^+$,

Then the following infimum

$$j := \inf_{u \in \mathcal{N}^- \cap \mathcal{E}^+} J(u)$$

is > 0 and it is achieved.

Proof. We know from Lemma 3.2(a) that $j \geq 0$. Observe that any minimizing sequence is bounded because (H6) implies the hypothesis (2.3) of Lemma 2.2 and the result comes from (ii) of the aforementioned lemma. Assume first that $j > 0$. We claim that there is a strong convergent minimizing sequence for j . Assume by contradiction that we have a minimizing sequence $u_n \rightharpoonup u_0$ such that $A(u_n) \rightarrow A(u_0), B(u_n) \rightarrow B(u_0)$ but $u_n \not\rightarrow u_0$. If $u_0 = 0$ then Lemma

2.1 will imply that $u_n \rightarrow 0$, which is not the case we are assuming now. Thus $u_0 \neq 0$. We can also prove that $B(u_0) > 0$ by using the fact that $u_n \in \mathcal{E}^+$ and

$$\frac{q-r}{qr}B(u_n) = J(u_n) - \left(\frac{1}{p} - \frac{1}{r}\right)E(u_n) \geq J(u_n).$$

Then passing to the limit we get $B(u_0) > 0$. Consequently, **(H6)** implies that $E(u_0) > 0$. Now we distinguish two cases according to the sign of $A(u_0)$.

Alt. 1. $A(u_0) > 0$. In this case J_{u_0} and J_{u_n} look like Fig. 2b. If $u_n \not\rightarrow u_0$ then $t_2(u_0) \neq 1$. We also have that $t_2(u_0)u_0 \in \mathcal{N}^- \cap \mathcal{E}^+$ (we use here that $\lambda_*^+ > 1$ to assure that $t_2(u_0)u_0 \notin \mathcal{N}_0$, c.f. Lemma 2.5). Furthermore

$$0 = J'_{u_0}(t_2(u_0)) < \liminf J'_{u_n}(t_2(u_0)).$$

Thus $J'_{u_n}(t_2(u_0)) > 0$ for n large. Since $t_2(u_n) = 1$ hence $t_1(u_n) < t_2(u_0) < 1$ and we will have

$$j \leq J_{u_0}(t_2(u_0)) < \liminf J_{u_n}(t_2(u_0)) \leq \lim_{n \rightarrow +\infty} J_{u_n}(1) = j, \tag{3.6}$$

a contradiction.

Alt. 2. $A(u_0) \leq 0$. In this case J_{u_0} and J_{u_n} look like Fig. 2c. If $u_n \not\rightarrow u_0$ then $t(u_0) \neq 1$. We also have that $t(u_0)u_0 \in \mathcal{N}^- \cap \mathcal{E}^+$. Then again we have

$$j \leq J_{u_0}(t(u_0)) < \liminf J_{u_n}(t(u_0)) \leq \lim_{n \rightarrow +\infty} J_{u_n}(1) = j, \tag{3.7}$$

a contradiction.

Let us finally prove that $j > 0$. If this were not the case then for any minimizing sequence (which we know that will be bounded) we will have $J(u_n) \rightarrow 0$. Then, up to a subsequence, there exists $u_0 \in X$ such that $u_n \rightarrow u_0$, $A(u_n) \rightarrow A(u_0)$ and $B(u_n) \rightarrow B(u_0)$. From Lemma 3.2(a) we know that $\mathcal{N}^- \cap \mathcal{E}^+ \subset \mathcal{B}^+$ and hence the possibility $u_0 = 0$ is excluded from Lemma 2.3 and **(H6)** applied to $C = \mathcal{B}_0^+$, so (2.4) is satisfied. Besides by writing

$$0 = \lim_{n \rightarrow +\infty} J(u_n) = \lim_{n \rightarrow +\infty} \left(\frac{1}{p} - \frac{1}{r}\right)E(u_n) + \left(\frac{1}{r} - \frac{1}{q}\right)B(u_n)$$

it comes

$$\lim_{n \rightarrow +\infty} E(u_n) = \frac{p(q-r)}{q(p-r)}B(u_0). \tag{3.8}$$

Thus, if $B(u_0) = 0$ then $E(u_0) \leq \lim_{n \rightarrow +\infty} E(u_n) = 0$, a contradiction with **(H6)**.

Hence $B(u_0) > 0$. Furthermore, from (3.8) and

$$0 = \lim_{n \rightarrow +\infty} J(u_n) = \lim_{n \rightarrow +\infty} \left(\frac{1}{p} - \frac{1}{q}\right)E(u_n) - \left(\frac{1}{r} - \frac{1}{q}\right)A(u_n)$$

it comes $A(u_0) = \frac{r(q-p)}{q(p-r)}B(u_0) > 0$. We are going to rule out the following two alternatives: Alt. 1. $u_n \rightarrow u_0$. In this case $J(u_0) = 0$ and we will have $u_0 \in \mathcal{N}^- \cap \mathcal{E}^+$ (the possibility of $u_0 \in \mathcal{N}_0$ is ruled by the constraint $\lambda_*^+ > 1$). But, according to Lemma 3.2(a), $J(u_0) > 0$, a contradiction.

Alt. 2. $u_n \not\rightarrow u_0$. The maps J_{u_0} will look as in Fig. 2b and repeating the argument of Alt. 1 above we have (3.6) and we reach a contradiction. This concludes the proof of $j > 0$. □

4. Local minimizers of J restricted to the Nehari set and to \mathcal{E}^-

4.1. Minimizing J along \mathcal{N}^+

We first look for solutions of our problem in $\mathcal{N}^+ \cap \mathcal{A}^- \subset \mathcal{N}^+ \cap \mathcal{E}^-$.

Theorem 4.1. *Assume that $\mathcal{N}^+ \cap \mathcal{A}^- \neq \emptyset$, $\lambda_*^- > 1$ and*

(H7) $\mathcal{A}_0^- \cap \mathcal{B}_0 \setminus \{0\} \subset \mathcal{E}^+$

(H8) $\mathcal{A}_0 \cap \mathcal{B}^- \subset \mathcal{E}^+$.

Then the following infimum

$$l := \inf_{u \in \mathcal{N}^+ \cap \mathcal{A}^-} J(u)$$

is < 0 and it is achieved.

Proof. It comes from **(H7)** and Lemma 2.2(i) that $\mathcal{N}^+ \cap \mathcal{A}^-$ is bounded and by Lemma 3.2(a) that l is negative. Let us prove that this infimum is achieved. Let u_n be a minimizing sequence. Since this sequence is bounded, there exists u_0 such that $u_n \rightharpoonup u_0$, $A(u_n) \rightarrow A(u_0)$ and $B(u_n) \rightarrow B(u_0)$. Thus $A(u_0) \leq 0$, $B(u_0) \leq 0$ and $E(u_0) \leq \liminf E(u_n) \leq 0$. From $E(u_n) \leq 0$ and

$$J(u_n) = \left(\frac{1}{p} - \frac{1}{r}\right) E(u_n) + \left(\frac{1}{r} - \frac{1}{q}\right) B(u_n)$$

we infer that

$$B(u_n) \leq \frac{rq}{q-r} J(u_n)$$

and passing to the limit it comes that $B(u_0) < 0$. In particular $u_0 \neq 0$. Now, if $A(u_0) = 0$, using **(H8)** we will conclude that $E(u_0) > 0$, a contradiction. Then $A(u_0) < 0$ and J_{u_0} behaves either as in Fig. 2d if $E(u_0) = 0$ or as in Fig. 2f if $E(u_0) < 0$. Let us discuss this two alternatives:

Alt. 1. $E(u_0) = 0$. In this case $E(u_0) = 0 = \liminf E(u_n) = 0$ so $u_n \rightarrow u_0$ by **(H3)**. Hence $J(u_0) = l$ and also $u_0 \in \mathcal{N}_0^+ \cap \mathcal{A}^-$. Since $u_0 \in \mathcal{N}_0^+$ implies that $E(u_0) = \frac{q-r}{q-p} A(u_0)$ by (3.4) and we know that $A(u_0) < 0 = E(u_0)$, then clearly $u_0 \notin \mathcal{N}_0^+$, so have $u_0 \in \mathcal{N}^+ \cap \mathcal{A}^-$ and we are done.

Alt. 2. $E(u_0) < 0$. In this case there exist two values $0 \leq t_1(u_0) < t_2(u_0)$ such that $t_2(u_0) > 0$ is a global minimum value for J_{u_0} , $t_2(u_0)u_0 \in \mathcal{N}^+ \cap \mathcal{A}^-$ and J_{u_0} is decreasing between $t_1(u_0)$ and $t_2(u_0)$, increasing elsewhere. Notice that $u_0 \notin \mathcal{N}_0^+$ because of condition $\lambda_*^- > 1$. Let us assume by contradiction that $u_n \not\rightarrow u_0$. Then

$$l \leq J(t_2(u_0)u_0) = J_{u_0}(t_2(u_0)) \leq J_{u_0}(1) < \liminf J_{u_n}(1) = \lim J(u_n) = l,$$

a contradiction. □

4.2. Minimizing J along \mathcal{N}^-

Finally we minimize along $\mathcal{N}^- \cap \mathcal{B}^- \subset \mathcal{N}^- \cap \mathcal{E}^-$.

Theorem 4.2. *Assume that $\mathcal{N}^- \cap \mathcal{B}^- \neq \emptyset$, $\lambda_*^- > 1$, **(H7)** and*

(H9) $\mathcal{A}_0 \cap \mathcal{B}_0^- \setminus \{0\} \subset \mathcal{E}^+$.

Then the infimum

$$k := \inf_{u \in \mathcal{N}^- \cap \mathcal{B}^-} J(u)$$

is achieved and it is positive.

Proof. By Lemma 3.2(a) the value $k \geq 0$. Since $\mathcal{N}^- \cap \mathcal{B}^- \subset \mathcal{A}^-$, Lemma 2.2(ii) and (H7) imply that any minimizing sequence is bounded. We claim that any minimizing sequence u_n possesses a convergence subsequence. Indeed, assume $u_n \rightharpoonup u_0$, $A(u_n) \rightarrow A(u_0) \leq 0$ and $B(u_n) \rightarrow B(u_0) \leq 0$ and that $u_n \not\rightarrow u_0$. Since $u_n \in \mathcal{N}^-$ we have $E(u_n) \leq \frac{q-r}{p-r} B(u_n) \leq 0$ so $E(u_0) \leq 0$. Let us assume first that $k \neq 0$. If $u_0 = 0$ then from Lemma 2.1 it comes that $u_n \rightarrow 0$ and therefore $0 = \lim J(u_n) = k$, a contradiction. Thus $u_0 \neq 0$. From hypothesis (H7) and (H9) we must have $u_0 \in \mathcal{A}^- \cap \mathcal{B}^-$. Hence J_{u_0} looks like Fig. 2f if $E(u_0) < 0$ or like Fig. 2d if $E(u_0) = 0$. Let us to discuss this two alternatives. Alt. 1. $E(u_0) = 0$. As we have $E(u_0) = 0 = \liminf E(u_n)$ then $u_n \rightarrow u_0$. Hence, using that $u_n \in \mathcal{N}$ and passing to the limit we find $0 = E(u_0) = A(u_0) + B(u_0) \leq 0$ so it must be $A(u_0) = B(u_0) = 0$, a contradiction with (H7) or (H9). We have ruled out this alternative.

Alt. 2. $E(u_0) < 0$. Thus there exists $0 < t_1(u_0) < t_2(u_0)$ such that $t_1(u_0)u_0 \in \mathcal{N}^-$ and $t_1(u_n) = 1$. We have used here that $t_1(u_0)u_0 \notin \mathcal{N}_0$ because of the hypothesis $\lambda_*^- > 1$. Let us assume by contradiction that $u_n \not\rightarrow u_0$. Hence

$$0 = J'_{u_0}(t_1(u_0)) < \liminf J'_{u_n}(t_1(u_0))$$

which implies that $J'_{u_n}(t_1(u_0)) > 0$ for n large. Thus $t_1(u_0) < 1$ or $t_1(u_0) > t_2(u_n)$ because J_{u_n} looks like Fig. 2f. In the first case we have

$$k \leq J(t_1(u_0)u_0) = J_{u_0}(t_1(u_0)) < \liminf J_{u_n}(t_1(u_0)) < \liminf J_{u_n}(1) = k,$$

a contradiction. In the second case let us suppose, up to a subsequence, that $t_2(u_n)$ converges to some $s \in [1, t_1(u_0)]$. We have

$$J'_{u_0}(s) < \liminf J'_{u_n}(t_2(u_n)) = 0,$$

which is a contradiction because $J'_{u_0} > 0$ on $(0, t_1(u_0))$. We have just proved that the minimizing sequence converges strongly and consequently the infimum k is achieved.

To finish the proof let us check that $k > 0$. Assume by contradiction that $k = 0$ and take u_n a minimizing sequence. Since u_n is bounded (as above) then we can assume that $u_n \rightharpoonup u_0$ for some u_0 . We have $B(u_0) \leq 0$, $A(u_0) \leq 0$ and $u_0 \in \mathcal{E}_0^-$. It follows from Lemma 2.3 and (H9) that $u_0 \neq 0$ and from the fact that $u_n \in \mathcal{N}^-$ we have

$$A(u_n) > \frac{pqr}{(q-r)(r-p)} J(u_n).$$

Hence passing to the limit we get $A(u_0) = 0$. Thus $u_0 \in \mathcal{A}_0 \cap \mathcal{B}_0^- \cap \mathcal{E}_0^-$ which contradicts (H9) if $B(u_0) \neq 0$ or (H7) if $B(u_0) = 0$. □

5. On various conditions for coerciveness and existence results

5.1. On the coerciveness of E restricted to \mathcal{A}_0^\pm and \mathcal{B}_0^\pm

We want to give in this section some variational conditions on E, A, B that would imply hypothesis **(H4)**–**(H9)**. Those conditions will concern the following constants of coerciveness

$$\begin{aligned} i^\pm(A) &:= \inf \{E(u) ; A(u) = \pm 1\}, \\ i^\pm(B) &:= \inf \{E(u) ; B(u) = \pm 1\}, \end{aligned} \tag{5.1}$$

$$\begin{aligned} j_0(A) &:= \inf \{E(u) ; A(u) = 0, u \in \mathcal{S}\}, \\ j_0(B) &:= \inf \{E(u) ; B(u) = 0, u \in \mathcal{S}\}. \end{aligned} \tag{5.2}$$

Recall that \mathcal{S} is the unit sphere of X . We give below and existence and multiplicity result for the equation $J'(u) = 0$ in terms of the constants j_0, i^\pm .

Theorem 5.1. *Let us assume hypothesis **(H1)** to **(H3)**.*

- (i) *If $\lambda_*^+ > 1, \mathcal{N}^+ \cap \mathcal{E}^+ \neq \emptyset, i^+(A) > 0$ and either $j_0(A) > 0$ or $j_0(B) > 0$ then there exists at least one solution of $J'(u) = 0$ in $\mathcal{N}^+ \cap \mathcal{E}^+$.*
- (ii) *If $\lambda_*^+ > 1, \mathcal{N}^- \cap \mathcal{E}^+ \neq \emptyset, j_0(B) > 0$ and $i^+(B) > 0$ then there exists at least one solution of $J'(u) = 0$ in $\mathcal{N}^- \cap \mathcal{E}^+$.*
- (iii) *If $\lambda_*^- > 1, \mathcal{N}^+ \cap \mathcal{A}^- \neq \emptyset$ and either*
 - (1) *$j_0(A) > 0$ and $i^-(A) > 0$ or*
 - (2) *$j_0(B) > 0$ and $j_0(A) > 0$ or*
 - (3) *$j_0(B) > 0$ and $i^-(B) > 0,$**then there exists at least one solution of $J'(u) = 0$ in $\mathcal{N}^+ \cap \mathcal{A}^- \subset \mathcal{N}^+ \cap \mathcal{E}^-$.*
- (iv) *If $\lambda_*^- > 1, \mathcal{N}^- \cap \mathcal{B}^- \neq \emptyset$ and either*
 - (4) *$j_0(A) > 0$ and $j_0(B) > 0$ or*
 - (5) *$j_0(A) > 0$ and $i^-(A) > 0$ or*
 - (6) *$j_0(B) > 0$ and $i^-(B) > 0,$**then there exists at least one solution of $J'(u) = 0$ in $\mathcal{N}^- \cap \mathcal{B}^- \subset \mathcal{N}^- \cap \mathcal{E}^-$.*

We left the proof to the reader. In the next proposition we give a variational characterization of $i^\pm(A)$ and $i^\pm(B)$.

Proposition 5.2. *Let us assume hypothesis **(H1)** to **(H3)**. Assume that $j_0(A) > 0$ and that $i^\pm(A) \in \mathbb{R}$. Then there exists $\varphi_\pm \in X$ satisfying $A(\varphi_\pm) = \pm 1$ such that*

$$E'(\varphi_\pm) = \frac{p}{r} i^\pm(A) A'(\varphi_\pm).$$

Similarly, if $j_0(B) > 0$ and $i^\pm(B) \in \mathbb{R}$ then there exists $\phi_\pm \in X$ satisfying $B(\phi_\pm) = \pm 1$ such that

$$E'(\phi_\pm) = \frac{p}{q} i^\pm(B) B'(\phi_\pm).$$

Proof. We only prove the first part. If $u_n \in X$ with $A(u_n) = 1$ is a minimizing sequence for, say, $i^+(A)$ then the sequence u_n is bounded. Indeed, otherwise if we take $v_n := \frac{u_n}{\|u_n\|}$ hence, up to a subsequence, there exists $v_0 \in X$ such that $v_n \rightharpoonup v_0, A(v_n) \rightarrow 0$ and $E(v_n) \rightarrow 0$. Notice that $v_0 \neq 0$ because otherwise it will follow from $0 = E(v_0) \leq \liminf E(v_n) = 0$ and **(H3)** that $v_n \rightarrow 0$. This

is impossible since $\|v_n\| = 1$. We then have $v_0 \neq 0$, $A(v_0) = 0$ and $E(v_0) \leq \liminf E(v_n) = 0$, a contradiction with the hypothesis $j_0(A) > 0$. We have just proved that u_n is bounded. The proof that $i^+(A)$ is achieved is standard and we omit it here. Let us denote by φ_+ an element of X where the infimum is achieved. From the Lagrange multipliers rule it follows that there exists $\lambda \in \mathbb{R}$ such that $E'(\varphi_+) = \lambda A'(\varphi_+)$. By testing this last equation against φ_+ and using the different homogeneities of E and A we get the result. \square

Remark 5.3. As a matter of fact the constraint $A(u) = 1$ in the definition of $i^+(A) := i^+(A, 1)$ can be replaced by, say, $A(u) = c$, where c in any positive number. In that case, it is trivial to prove that $i^+(A, c) = c^{\frac{E}{A}} i^+(A, 1)$. A similar statement can be formulated for $i^-(A)$ and $i^\pm(B)$.

Remark 5.4. We can easily prove that $j_0(A)$ and $j_0(B)$ are achieved provided they are finite and $j_0(A, B) := \inf\{E(u) ; A(u) = 0, B(u) = 0, u \in \mathcal{S}\} > 0$. However we can not give a variational formulation of any of them mainly because, in general, we don't know if the set $A^{-1}(\{0\})$ (resp. $B^{-1}(\{0\})$) is a manifold.

5.2. On the coerciveness of E and a principal eigenvalue

In this section we look for sufficient conditions implying **(H4)** to **(H9)** in terms of the *first eigenvalue* of the operator E . Precisely, let us assume the following

$$(\mathbf{H3})' \begin{cases} \exists(Y, \|\cdot\|_Y) \text{ a Banach space s.t. } X \text{ is cont. one-to-one embeded on } Y, \\ X \hookrightarrow Y \text{ is compact and } u \rightarrow \|u\|_Y^p \text{ is Fréchet differentiable.} \end{cases}$$

Let us denote $\chi(u) = \|u\|_Y^p$. Then it is straightforward from **(H2)**–**(H3)**' that

$$\lambda_1 := \inf \{E(u) ; \|u\|_Y = 1\} \tag{5.3}$$

is $> -\infty$ and it is achieved. Moreover, if $E(\varphi) = \lambda_1$ and $\|\varphi\|_Y = 1$ then, by Lagrange multiplier rule, $E'(\varphi) = \lambda_1 \chi'(\varphi)$.

We can give now the following sufficient conditions in terms of λ_1 to assure **(H4)**–**(H9)**. Notice that the following conditions are stronger than the ones in terms of $i^\pm(A)$, $i^\pm(B)$ etc. Let us also stress here that $\lambda_1 > 0$ is equivalent to $\mathcal{E}_0^- \setminus \{0\} = \emptyset$ and therefore **(H4)** to **(H9)** are trivially satisfied. Hereafter we denote

$$E_{\lambda_1} := \{\varphi \in X \setminus \{0\} ; E'(\varphi) = \lambda_1 \chi'(\varphi)\}.$$

We have

Proposition 5.5. *Let us assume **(H1)** to **(H3)**' and $\lambda_1 = 0$. Then*

- (a) $E_{\lambda_1} \cap \mathcal{A}_0^+ \cap \mathcal{B}_0 = \emptyset \Rightarrow \mathbf{(H4)}$,
- (b) $E_{\lambda_1} \subset \mathcal{A}^- \Rightarrow j_0(A) > 0, i^+(A) > 0 \Rightarrow j_0(A) > 0$ and **(H5)**,
- (c) $E_{\lambda_1} \subset \mathcal{B}^- \Rightarrow j_0(B) > 0, i^+(B) > 0 \Rightarrow \mathbf{(H6)}$.

Proof. We only prove (b), the proof of the other cases are similar. Trivially $i^+(A) \geq \lambda_1 = 0$ and $j_0(A) \geq \lambda_1 = 0$. Assume by contradiction that $i^+(A) = 0$ and let $u_n \in X$ with $A(u_n) = 1$ be a minimizing sequence for $i^+(A)$. If the sequence u_n is bounded then, up to a subsequence, $u_n \rightharpoonup u_0$ for some $u_0 \in X$. Hence $A(u_0) = 1$ (so in particular $u_0 \neq 0$) and $E(u_0) = i^+(A) = 0$. Hence

$0 = \lambda_1 = E\left(\frac{u_0}{\|u_0\|_Y}\right)$ so $\frac{u_0}{\|u_0\|_Y}$ is an eigenfunction associated to λ_1 and we have again a contradiction with the assumption of (b). Thus the sequence (u_n) is unbounded. Let us take $v_n := \frac{v_n}{\|u_n\|}$; hence there exists $v_0 \in X$ such that, up to a subsequence, $v_n \rightharpoonup v_0$, $A(v_n) \rightarrow 0$ and $E(v_n) \rightarrow 0$. Notice that $v_0 \neq 0$ because otherwise it will follow from $0 = E(v_0) \leq \liminf E(v_n) = 0$ and **(H3)** that $v_n \rightarrow 0$. This is impossible since $\|v_n\| = 1$. We then have $v_0 \neq 0$, $A(v_0) = 0$ and $E(v_0) \leq 0$. By using the inequality

$$0 = \lambda_1 \leq E\left(\frac{v_0}{\|v_0\|_Y}\right)$$

we deduce that $E(v_0) = 0$ so v_0 belongs to E_{λ_1} , a contradiction with the assumption of (b). The proof of $j_0(A) > 0$ rules similarly. \square

We can obtain two more solutions of $J'(u) = 0$ in the case $\lambda_1 < 0$, that is, when $\mathcal{E}^- \neq \emptyset$. To do so, let us assume in this case that

$$\text{(H3)}'' \quad \sigma_Y(E) := \{\lambda \in \mathbb{R} ; \exists u \in X \setminus \{0\}, E'(u) = \lambda \chi'(u)\} \subset \{\lambda_1\} \cup]0, +\infty[.$$

We have

Proposition 5.6. *Let us assume hypothesis **(H1)** to **(H3)**. Then*

- (a) $j_0(A) > 0 \Rightarrow$ **(H8)** and **(H9)**,
- (b) $j_0(B) > 0 \Rightarrow$ **(H4)** and **(H7)**.

*Let us assume also hypothesis **(H3)'** and **(H3)''**. Then*

- (c) $j_0(A) > 0$ and $E_{\lambda_1} \subset \mathcal{A}^- \Rightarrow$ **(H4)** and $i^+(A) > 0 \Rightarrow$ **(H4)** and **(H5)**,
- (d) $j_0(B) > 0$ and $E_{\lambda_1} \subset \mathcal{B}^- \Rightarrow$ **(H4)** and $i^+(B) > 0 \Rightarrow$ **(H4)** and **(H6)**.

Proof. (a), (b) are trivial. We only prove (c) as the proof of (d) is similar. Let us denote

$$d := \inf\{E(u); A(u) \geq 0, \|u\|_Y = 1\}$$

and prove that $d > 0$. Clearly $d > 0 \Rightarrow$ **(H4)**. Since for all $u \in X$ satisfying $A(u) = 1$ we have $E(\frac{u}{\|u\|_Y}) \geq d$, the conclusion $i^+(A) > 0$ will follow, and also **(H5)**.

First we claim that d is achieved. Indeed, if u_n is an admissible sequence with $E(u_n) \rightarrow d$ then we can prove that the sequence is bounded (otherwise the sequence $v_n = \frac{u_n}{\|u_n\|}$ will satisfy $E(v_n) \rightarrow 0, \|v_n\|_Y \rightarrow 0$, so, up to a subsequence, $v_n \rightharpoonup 0$, in contradiction with **(H3)** and the fact that $\|v_n\| = 1$). Let $u_0 \in X$ be such that $u_n \rightharpoonup u_0$. Thus $A(u_0) \geq 0, \|u_0\|_Y = 1$ and consequently $d \leq E(u_0) \leq \liminf E(u_n) = d$. We have proved that $E(u_0) = d$ and d is achieved. If $A(u_0) = 0$ hence $d \geq j_0(A) > 0$ and we are done. If $A(u_0) > 0$ hence

$$d = \inf\{E(u); A(u) > 0, \|u\|_Y = 1\}$$

and d is then a local minima of E under the constrain $\|u\|_Y = 1$. By Lagrange multiplier rule, there exists $\lambda \in \mathbb{R}$ such that $E'(u_0) = \lambda\chi'(u_0)$. By evaluating this equation at u_0 we readily obtain

$$pd = pE(u_0) = \langle E'(u_0), u_0 \rangle = \lambda \langle \chi'(u_0), u_0 \rangle = p\lambda.$$

Since $E_{\lambda_1} \subset \mathcal{A}^-$ then $\lambda \neq \lambda_1$ and therefore $d = \lambda > 0$ by **(H3)''**. □

We can now give the first main existence result of this section. This result generalizes Theorems 4.8 and 5.7 of [16].

Theorem 5.7. *Let us assume hypotheses **(H1)** to **(H3)'**.*

- (i) *Assume that $\mathcal{N}^\pm \cap \mathcal{E}^+ \neq \emptyset$ and $\lambda_*^+ > 1$. If either $\lambda_1 > 0$ or $\lambda_1 = 0$ and $E_{\lambda_1} \subset \mathcal{A}^- \cap \mathcal{B}^-$ then there exists at least two solutions of $J'(u) = 0$.*
- (ii) *Assume that $\mathcal{N}^+ \cap \mathcal{E}^+ \neq \emptyset$ and $\lambda_*^+ > 1$. If $\lambda_1 = 0$ and $E_{\lambda_1} \subset \mathcal{A}^- \cap \mathcal{B}_0^+$ then there exists at least one solution of $J'(u) = 0$.*
- (iii) *Assume that $\mathcal{N}^+ \cap \mathcal{A}^- \neq \emptyset$, $\mathcal{N}^- \cap \mathcal{B}^- \neq \emptyset$ and $\lambda_*^- > 1$. If $j_0(A) > 0$ and $j_0(B) > 0$ then there exist at least two solutions of $J'(u) = 0$ in \mathcal{E}^- .*
- (iv) *Assume **(H3)''**, $\mathcal{N}^+ \cap \mathcal{E}^+ \neq \emptyset$, $\lambda_*^+ > 1$ and $\lambda_1 < 0$. If $j_0(A) > 0$ and $E_{\lambda_1} \subset \mathcal{A}^-$ then there exist at least one solution of $J'(u) = 0$ in \mathcal{E}^+ .*
- (v) *Assume **(H3)''**, $\mathcal{N}^\pm \cap \mathcal{E}^+ \neq \emptyset$, $\lambda_*^+ > 1$ and $\lambda_1 < 0$. If $j_0(A) > 0$, $j_0(B) > 0$ and $E_{\lambda_1} \subset \mathcal{A}^- \cap \mathcal{B}^-$ then there exist at least two solutions of $J'(u) = 0$ in \mathcal{E}^+ .*

Proof. (i) Clearly we have **(H4)**, **(H5)** and **(H6)** from Proposition 5.5. Thus the local minimum of Theorem 3.3 provides us a first solution of $J'(u) = 0$. Since we also have **(H6)**, a second solution comes from Theorem 3.4.
 (ii) We have **(H4)** and **(H5)** from Proposition 5.5 (a)–(b). Thus the local minimum of Theorem 3.3 is a solution of $J'(u) = 0$.
 (iii) From (a) and (b) of Proposition 5.6 the hypotheses **(H7)**, **(H8)** and **(H9)** hold. Then we get two solutions from Theorems 4.1 and 4.2.
 (iv) From (c) of Proposition 5.6 the hypotheses **(H4)** and **(H5)** hold. Then we get one solution from Theorem 3.3.
 (v) From (c) and (d) of Proposition 5.6 the hypotheses **(H4)**, **(H5)**, **(H6)** and **(H7)** hold. Then we get two solutions from Theorems 3.3 and 3.4. □

5.3. A variational characterization of λ_*^\pm

We have proved in the previous section the existence of four solutions of the equation $J'(u) = 0$ provided $\lambda_*^\pm > 1$, where λ_*^\pm has been defined in (2.8) and (2.9). Let us here give some variational characterization of these values. For the sake of simplicity let us denote

$$\alpha := \frac{p-r}{q-r}, \quad \beta := \frac{q-p}{q-r},$$

so it holds

$$0 < \alpha, \beta < 1, \quad \alpha + \beta = 1, \quad q\alpha + r\beta = p.$$

Observe that

$$\begin{aligned} (\lambda_*^+)^{\beta} &= \beta^{\beta} \alpha^{\alpha} \inf\{E(u); u \in \mathcal{E}^+ \cap \mathcal{A}^+ \cap \mathcal{B}^+, A(u)^{\beta} B(u)^{\alpha} = 1\}, \\ (\lambda_*^-)^{\beta} &= \beta^{\beta} \alpha^{\alpha} \inf\{-E(u); u \in \mathcal{E}^- \cap \mathcal{A}^- \cap \mathcal{B}^-, (-A(u))^{\beta} (-B(u))^{\alpha} = 1\}. \end{aligned}$$

Proposition 5.8. *Let us define*

$$j_0^+(A, B) := \inf \{E(u) ; u \in \mathcal{A}_0^+ \cap \mathcal{B}_0^+ \cap \mathcal{S}\} \tag{5.4}$$

$$j_0^-(A, B) := \inf \{E(u) ; u \in \mathcal{A}_0^- \cap \mathcal{B}_0^- \cap \mathcal{S}\}. \tag{5.5}$$

If $j_0^+(A, B) > 0$ then λ_*^+ is achieved. Furthermore, for any $u \in X$ where λ_*^+ is achieved we have

$$E'(u) = \frac{(\beta/\alpha)^\alpha (\lambda_*^+)^\beta}{A(u)} A'(u) + \frac{(\alpha/\beta)^\beta (\lambda_*^+)^\beta}{B(u)} B'(u) \tag{5.6}$$

A similar result holds for λ_*^- under the constraint $j_0^-(A, B) > 0$.

Proof. If $u_n \in \mathcal{A}^+ \cap \mathcal{B}^+ \cap \mathcal{E}^+$ with $A(u_n)^\beta B(u_n)^\alpha = 1$ is a minimizing sequence for λ_*^+ and (u_n) is bounded then, up to a subsequence, $u_n \rightharpoonup u_0$ for some $u_0 \in X$ that will satisfy $A(u_0)^\beta B(u_0)^\alpha = 1$, so u_0 will be admissible in the infimum and then it is achieved. If $\|u_n\|$ goes to $+\infty$ then for $v_n = \frac{u_n}{\|u_n\|}$ we will have, up to a subsequence, $v_n \rightharpoonup v_0$ for some $v_0 \in X$, $A(v_n)^\beta B(v_n)^\alpha = \frac{1}{\|u_n\|^p} \rightarrow 0$ and $E(v_0) \leq \liminf \frac{E(u_n)}{\|u_n\|^p} = 0$. We can rule out the possibility $v_0 = 0$, since in this case $E(v_0) = 0 = \liminf E(v_n)$ and then, from **(H3)**, $v_n \rightarrow v_0$ which is impossible because $\|v_n\| = 1$. Thus $v_0 \in \mathcal{E}_0^- \cap \mathcal{A}_0^+ \cap \mathcal{B}_0^+$, a contradiction with the constraint $j_0^+(A, B) > 0$. Let us denote $\Phi(v) := A(v)^\beta B(v)^\alpha$ and observe that $\Phi^{-1}\{1\}$ is a C^1 -manifold. By Lagrange Multiplier rule we have that for any $u \in \Phi^{-1}(1)$ with $E(u) = \frac{(\lambda_*^+)^\beta}{\alpha^\alpha \beta^\beta}$ there exists $\mu \in \mathbb{R}$ such that $E'(u) = \mu \Phi'(u)$. Testing this identity at u we have

$$\langle E'(u), u \rangle = \mu(\beta B(u)^\alpha A(u)^{\beta-1} \langle A'(u), u \rangle + \alpha A(u)^\beta B(u)^{\alpha-1} \langle B'(u), u \rangle)$$

that is $pE(u) = \mu(r\beta + q\alpha) = \mu p$ and the identity (5.6) follows after a simple computation. \square

Remark 5.9. As in Proposition 5.5 one has

- (i) $\lambda_1 > 0 \Rightarrow j_0^\pm(A, B) > 0$,
- (ii) If $\lambda_1 = 0$ then

- (1) $E_{\lambda_1} \cap \mathcal{A}_0^+ \cap \mathcal{B}_0^+ = \emptyset \Rightarrow j_0^+(A, B) > 0$.
- (2) $E_{\lambda_1} \cap \mathcal{A}_0^- \cap \mathcal{B}_0^- = \emptyset \Rightarrow j_0^-(A, B) > 0$.

Let us show that, in a particular case, the variational equation (5.6) is equivalent to the equation $J'(u) = 0$. By *equivalent* we mean here that a multiple of a solution of (5.6) is a solution of $J'(u)$. Let us observe that if $\varphi \in X \setminus \{0\}$ is a solution of (5.6) and we denote for simplicity

$$d_1 := \frac{(\beta/\alpha)^\alpha (\lambda_*^+)^\beta}{A(\varphi)}, \quad d_2 := \frac{(\alpha/\beta)^\beta (\lambda_*^+)^\beta}{B(\varphi)} \tag{5.7}$$

then for any $c > 0$ the function $v = c\varphi$ satisfies

$$E'(v) = d_1 c^{p-r} A'(v) + d_2 c^{p-q} B'(v).$$

Thus we have the following result

Proposition 5.10. *Assume that $j_0^+(A, B) > 0$ and that*

$$(\lambda_*^+)^{\beta} = \left(\frac{p}{r}\right)^{\beta} \cdot \left(\frac{p}{q}\right)^{\alpha}. \tag{5.8}$$

Then there exists a solution of $J'(u) = 0$ satisfying $u \in \mathcal{A}^+ \cap \mathcal{B}^+$. The constant $c_{pqr} := \left(\frac{p}{r}\right)^{\beta} \cdot \left(\frac{p}{q}\right)^{\alpha}$ is > 1 .

A similar result can be state for λ_*^+ if $j_0^-(A, B) > 0$.

Proof. Recall that $J'(u) = 0$ if and only if $E'(u) = \frac{p}{r}A'(u) + \frac{p}{q}B'(u)$. Let $\varphi \in X$ be a point where λ_*^+ is achieved. A simple computation shows that we can choose $c > 0$ such that $c\varphi$ is a critical point of J , that is, $d_1c^{p-r} = \frac{p}{r}$ and $d_2c^{p-q} = \frac{p}{q}$ if and only if

$$\left(\frac{\frac{p}{r}}{d_1}\right)^{\beta} \cdot \left(\frac{\frac{p}{q}}{d_2}\right)^{\alpha} = 1$$

and using the fact that $\alpha + \beta = 1$, $A(\varphi)^{\beta}B(\varphi)^{\alpha} = 1$ and (5.7) we get (5.8). Let us write

$$(c_{pqr})^{\frac{q-r}{r}} = \left(\frac{p}{r}\right)^{\frac{q}{r}-1} \cdot \left(\frac{q}{r}\right)^{1-\frac{p}{r}}.$$

One has

$$\frac{q-r}{r} \ln(c_{pqr}) = \left(\frac{q}{r} - 1\right) \ln \frac{p}{r} + \left(1 - \frac{p}{r}\right) \ln \frac{q}{r} = (x-1) \ln y - (y-1) \ln x,$$

where we have put $x := \frac{q}{r}$ and $y := \frac{p}{r}$. Using the fact that the function $f(z) := \frac{\ln z}{z-1}$ is strictly decreasing for $z > 1$ we conclude that $\frac{q-r}{r} \cdot \ln(c_{pqr}) > 0$ and therefore the constant $c_{pqr} > 1$ as claimed. \square

Remark 5.11. Notice that, if (5.8) holds, we can not distinguish the solution of the problem $J'(u) = 0$ obtained in Proposition 5.10 from the one obtained in Theorem 3.3 or the one in Theorem 3.4.

6. Existence results for quasilinear problems

6.1. Existence and multiplicity results for Problem I

Let $\Omega \subset \mathbb{R}^N$ be a bounded smooth domain of class $C^{2,\alpha}$ ($0 < \alpha < 1$) with outward unit normal ν on the boundary $\partial\Omega$. Let $V \in L^\infty(\Omega)$ and $(a, b) \in (C^s(\partial\Omega))^2$, for some $s \in (0, 1)$, and allow them to change sign. The exponents r, q to satisfy $1 < r < p < q < p_*$ where $p_* = \frac{p(N-1)}{(N-p)^+}$ the critical exponent for the trace embedding; ρ denotes the restriction to $\partial\Omega$ of the $(N-1)$ -Hausdorff measure, which coincides with the usual Lebesgue surface measure as $\partial\Omega$ is regular enough. Finally let the number λ be a positive parameter.

Take $X = W^{1,p}(\Omega)$ with the usual Sobolev norm $\|\cdot\|_{1,p}$. Solutions of Problem I are understood in the weak sense, that is,

$$\int_{\Omega} (|\nabla u|^{p-2} \nabla u \nabla \varphi + V(x)|u|^{p-2} u \varphi) = \int_{\partial\Omega} (\lambda a |u|^{r-2} u + b |u|^{q-2} u) \varphi \, d\rho. \tag{6.1}$$

$\forall \varphi \in W^{1,p}(\Omega)$. Let us consider

$$E(u) = \int_{\Omega} (|\nabla u|^p + V(x)|u|^p) dx, \quad A(u) = \lambda \int_{\partial\Omega} a(\rho)|u|^r d\rho,$$

$$B(u) = \int_{\partial\Omega} b(\rho)|u|^q d\rho,$$

and the energy functional

$$J(u) = \frac{1}{p}E(u) - \frac{1}{r}A(u) - \frac{1}{q}B(u)$$

$$= \frac{1}{p} \int_{\Omega} (|\nabla u|^p + V(x)|u|^p) dx - \frac{\lambda}{r} \int_{\partial\Omega} a(\rho)|u|^r d\rho - \frac{1}{q} \int_{\partial\Omega} b(\rho)|u|^q d\rho.$$

It is clear that solutions of Problem I are positive critical points of J . It is also clear that A, B satisfy (2.1) and hypothesis (H1) since the trace operators $W^{1,p}(\Omega) \rightarrow L^r(\partial\Omega, \rho)$ and $W^{1,p}(\Omega) \rightarrow L^q(\partial\Omega, \rho)$ are compact (remember that $r, q < p_*$). Hypotheses (H2) and (H3) are well known properties of the p -laplacian operator, c.f. [18].

Let us consider the compact embedding $W^{1,p}(\Omega) \hookrightarrow Y = L^p(\Omega)$ and denote $\|\cdot\|_p$ the Lebesgue norm of $L^p(\Omega)$. The eigenvalue λ_1 defined in (5.3) takes the following expression:

$$\lambda_1 := \inf \left\{ \int_{\Omega} (|\nabla u|^p + V(x)|u|^p) dx ; u \in W^{1,p}(\Omega), \|u\|_p = 1 \right\}$$

and it corresponds to the least eigenvalue μ of the following eigenvalue problem with *Newman boundary conditions* :

$$\begin{cases} -\Delta_p u + V(x)|u|^{p-2}u = \mu|u|^{p-1}u & \text{in } \Omega, \\ |\nabla u|^{p-2} \frac{\partial u}{\partial \nu} = 0 & \text{on } \partial\Omega. \end{cases} \tag{6.2}$$

This problem should be understood in the weak sense, that is, for all $\varphi \in W^{1,p}(\Omega)$

$$\int_{\Omega} (|\nabla u|^{p-2} \nabla u \nabla \varphi + V(x)|u|^{p-2}u\varphi) dx = \mu \int_{\Omega} |u|^{p-2}u\varphi dx. \tag{6.3}$$

It is known (c.f. [6]) that λ_1 is simple and isolated in the sense that

$$\inf \{ \mu > \lambda_1 ; \mu \text{ solves (6.3) for some } u \in W^{1,p}(\Omega) \setminus \{0\} \} > \lambda_1.$$

We then have that hypothesis (H3)' is satisfied and that E_{λ_1} is of dimension 1. We will denote by φ_1 the unique eigenfunction of L^p -norm equal to 1 associated to λ_1 . It is also known that φ_1 is sign definite and never vanishes in $\overline{\Omega}$. Furthermore, there is a *second eigenvalue* λ_2 for problem (6.2) and it can be characterized as

$$\lambda_2 = \inf \{ \mu > \lambda_1 ; \mu \text{ solves (6.2) for some } u \in W^{1,p}(\Omega) \setminus \{0\} \}. \tag{6.4}$$

In order to apply Theorem 5.7 we are going first to determinate under which conditions on a, b, V the Nehari sign-sets used in Theorems 3.3, 3.4, 4.2,

4.1 are non empty. For this purpose we will use Proposition 2.4 of Sect. 2. Let us denote

$$\Gamma_a^\pm := \{\rho \in \partial\Omega ; a(\rho) \geq 0\}, \quad \Gamma_b^\pm := \{\rho \in \partial\Omega ; b(\rho) \geq 0\},$$

$$\Gamma_{a,0} := \{\rho \in \partial\Omega ; a(\rho) = 0\}, \quad \Gamma_{b,0} := \{\rho \in \partial\Omega ; b(\rho) = 0\}.$$

Lemma 6.1. (1) $\mathcal{E}^+ \neq \emptyset$.

(2) If $\Gamma_a^+ \neq \emptyset$ then $\mathcal{N}^+ \cap \mathcal{E}^+ \neq \emptyset$.

(3) If $\Gamma_b^+ \neq \emptyset$ then $\mathcal{N}^- \cap \mathcal{E}^+ \neq \emptyset$.

(4) If $\Gamma_a^- \cap \Gamma_b^- \neq \emptyset$ then $\mathcal{N}^+ \cap \mathcal{A}^- \neq \emptyset$ and $\mathcal{N}^- \cap \mathcal{B}^- \neq \emptyset$.

Proof. The proof of (1) is trivial and we only prove (2), the proofs of the other cases are similar.

(2) We distinguish two cases:

Case a) $\Gamma_a^+ \cap (\Gamma_b^- \cup \Gamma_{b,0}) \neq \emptyset$. In this case we can construct a C^∞ function v in $\partial\Omega$ such that $A(v) > 0 \geq B(v)$. Let $u \in W^{1,p}(\Omega)$ having v as its trace. Let ξ be a C^∞ cut function such that $0 \leq \xi \leq 1$, $\xi \equiv 1$ in a small ball $B(x_0, r) \subset \Omega$ where $|u| > c$ for some $c > 0$, $\xi \equiv 1$ in a neighbourhood $\Omega_\delta := \{x \in \bar{\Omega} ; \text{dist}(x, \partial\Omega) < \delta\}$ of $\partial\Omega$, and $\xi = 0$ in $\Omega \setminus (B(x, 2r) \cup \Omega_{2\delta})$. We can assume that

$$c^p \int_{B(x_0, 2r)} |\nabla \xi|^p \geq \int_{B(x_0, 2r)} |\xi|^p (|\nabla u|^p + V|u|^p) \tag{6.5}$$

which implies that $E(\xi u) > 0$. Thus $\xi u \in \mathcal{A}^+ \cap \mathcal{B}_0^- \cap \mathcal{E}^+$ and from Proposition 2.4 (i) we infer that $\mathcal{N}^+ \cap \mathcal{E}^+ \neq \emptyset$.

Case b) If $\Gamma_a^+ \subset \Gamma_b^+$ the construction of u and ξ runs similarly, starting with $v \in C^\infty(\partial\Omega)$ such that $A(v), B(v) > 0$. The cut function ξ can be chosen in such a way that (6.5) is satisfied as well as

$$A(\xi u) = A(v) < \left(\frac{q-p}{q-r}\right) \left(\frac{p-r}{q-r}\right)^{\frac{p-r}{q-p}} \frac{E(\xi u)^{\frac{q-r}{q-p}}}{B(\xi u)^{\frac{p-r}{q-p}}} = \max_{t>0} m_{\xi u}(t).$$

Thus $\xi u \in \Lambda^+$ and the conclusion follows from (i) of Proposition 2.4. □

We remember here the coerciveness values defined in (5.1), that in our case will be

$$j_0(a) := \inf \left\{ \int_{\Omega} |\nabla u|^p + V(x)|u|^p ; \int_{\partial\Omega} a|u|^r = 0, \|u\|_{1,p} = 1 \right\},$$

$$j_0(b) := \inf \left\{ \int_{\Omega} |\nabla u|^p + V(x)|u|^p ; \int_{\partial\Omega} b|u|^q = 0, \|u\|_{1,p} = 1 \right\}.$$

Finally let us recall the definitions (2.8) and (2.9) and write for sake of simplicity

$$\mu_+ := \inf_{u \in \mathcal{A}^+ \cap \mathcal{B}^+ \cap \mathcal{E}^+} \frac{\max_{t>0} m_u(t)}{\frac{A(u)}{\lambda}}$$

and

$$\mu_- := \inf_{u \in \mathcal{A}^- \cap \mathcal{B}^- \cap \mathcal{E}^-} \frac{\min_{t>0} m_u(t)}{\frac{A(u)}{\lambda}}$$

which do not depend on λ .

We can now reformulate Theorem 5.7 as the following existence and multiplicity result for Problem I.

- Theorem 6.2.** (i) Assume that $\Gamma_a^+ \neq \emptyset$ and $\Gamma_b^+ \neq \emptyset$. If either $\lambda_1 > 0$ or $\lambda_1 = 0$ and $\int_{\partial\Omega} a\varphi_1^r < 0$, $\int_{\partial\Omega} b\varphi_1^q < 0$ then there exists at least two solutions for any $\lambda \in (0, \mu_+^{-1})$.
- (ii) Assume that $\Gamma_a^+ \neq \emptyset$. If $\lambda_1 = 0$ and $\int_{\partial\Omega} a\varphi_1^r < 0$ then there exists at least one solution for any $\lambda \in (0, \mu_+^{-1})$.
- (iii) Assume that $\Gamma_a^- \cap \Gamma_b^- \neq \emptyset$. If $j_0(a) > 0$ and $j_0(b) > 0$ then there exist at least two solutions in \mathcal{E}^- for any $\lambda \in (0, \mu_-^{-1})$.
- (iv) Assume that $\Gamma_a^+ \neq \emptyset$. If $\lambda_1 < 0 < \lambda_2$, $j_0(a) > 0$ and $\int_{\partial\Omega} a\varphi_1^r < 0$ then there exist at least one solution in \mathcal{E}^+ for any $\lambda \in (0, \mu_+^{-1})$.
- (v) Assume that $\Gamma_a^+ \neq \emptyset$ and $\Gamma_b^+ \neq \emptyset$. If $\lambda_1 < 0 < \lambda_2$, $j_0(a) > 0$, $j_0(b) > 0$, $\int_{\partial\Omega} a\varphi_1^r < 0$, and $\int_{\partial\Omega} b\varphi_1^q < 0$ then there exist at least two solutions in \mathcal{E}^+ for any $\lambda \in (0, \mu_+^{-1})$.

In particular we have from cases (iii) and (v) that

Corollary 6.3. Assume that $\Gamma_a^+ \neq \emptyset$, $\Gamma_b^+ \neq \emptyset$ and $\Gamma_a^- \cap \Gamma_b^- \neq \emptyset$. If $\lambda_1 < 0 < \lambda_2$, $j_0(a) > 0$, $j_0(b) > 0$, $\int_{\partial\Omega} a\varphi_1^r < 0$, and $\int_{\partial\Omega} b\varphi_1^q < 0$ then Problem I possesses at least 4 solutions for any $\lambda \in (0, \min\{\mu_+^{-1}, \mu_-^{-1}\})$.

Proof of Theorem 6.2. The existence of weak solutions in each of the 4 cases have already be done in Theorem 5.7. Since each solution comes as a local minimizer of J along the sign subsets of the Nehari set and all of these subsets are invariant by taking the absolute value of a function u , we can assume that all these critical points are ≥ 0 . Besides the result of [6, Theorem A.1] implies that all solutions are bounded and the regularity result of [14] gives that they are of class $C^{1,\alpha}(\bar{\Omega})$ for some $\alpha \in (0, 1)$. Finally the Strong Maximum principle of [20] insures that non negative solutions of the problem are > 0 on $\bar{\Omega}$. \square

Remark 6.4. Unfortunately we are not able to replace the conditions $j_0(a) > 0$ and $j_0(b) > 0$ by, say, a condition related to some suitable eigenvalue. We just remark that both $j_0(a) > 0$ and $j_0(b) > 0$ imply that $\lambda_1^D > 0$, where λ_1^D denotes the first eigenvalue of $-\Delta_p + V|u|^{p-2}u$ with Dirichlet boundary conditions.

Remark 6.5. In the case $a \geq 0$ (resp. $b \geq 0$) and a "nice" zero set $\Gamma_{a,0}$ one should be able to relate the condition $j_0(a) > 0$ (resp $j_0(b) > 0$) with the positivity of the first eigenvalue of $-\Delta_p u + V|u|^{p-2}u$ over $W^{1,p}(\Omega, \Gamma_{a,0}) := \{u \in W^{1,p}(\Omega) ; u = 0 \text{ on } \partial\Omega \setminus \Gamma_{a,0}\}$, as was done in [7, Proposition 11].

6.2. Existence and multiplicity results for Problem II

Let $\Omega \subset \mathbb{R}^N$ be a bounded smooth domain of class $C^{2,\alpha}$ ($0 < \alpha < 1$) with outward unit normal ν on the boundary $\partial\Omega$. Let $a, V \in L^\infty(\Omega)$ and $b \in C^s(\partial\Omega)$ for some $s \in (0, 1)$ be possibly indefinite and the exponents r, q to satisfy $1 < r < p < q < p_*$ where $p_* = \frac{p(N-1)}{(N-p)^+}$ and let the number λ be a positive parameter. Take $X = W^{1,p}(\Omega)$ with the usual Sobolev norm $\|\cdot\|_{1,p}$, the operators

$$E(u) = \int_{\Omega} (|\nabla u|^p + V(x)|u|^p) \, dx, \quad A(u) = \lambda \int_{\Omega} a(x)|u|^r \, dx,$$

$$B(u) = \int_{\partial\Omega} b(\rho)|u|^q \, d\rho,$$

and the energy functional

$$J(u) = \frac{1}{p}E(u) - \frac{1}{r}A(u) - \frac{1}{q}B(u)$$

$$= \frac{1}{p} \int_{\Omega} (|\nabla u|^p + V(x)|u|^p) \, dx - \frac{\lambda}{r} \int_{\Omega} a(x)|u|^r \, dx - \frac{1}{q} \int_{\partial\Omega} b(\rho)|u|^q \, d\rho.$$

A, B satisfy (2.1) and hypothesis (H1) since the embedding $W^{1,p}(\Omega) \hookrightarrow L^r(\Omega)$ and the trace operator $W^{1,p}(\Omega) \rightarrow L^q(\partial\Omega, \rho)$ are compact (remember that $r, q < p_* < p^*$). Solutions of Problem II are understood in the weak sense, that is,

$$\int_{\Omega} (|\nabla u|^{p-2} \nabla u \nabla \varphi + V(x)|u|^{p-2} u \varphi) = \int_{\Omega} \lambda a |u|^{r-2} u \varphi \, dx + \int_{\partial\Omega} b |u|^{q-2} u \varphi \, d\rho, \tag{6.6}$$

for all $\varphi \in W^{1,p}(\Omega)$. Similar to the previous case, (H2) to (H3)^{''} are also satisfied with λ_1 defined in (6.2) and λ_2 as in (6.4). Let us consider again the compact embedding $W^{1,p}(\Omega) \hookrightarrow Y = L^p(\Omega)$ so the eigenvalues λ_1 and λ_2 have been already defined for Problem I. Let us denote

$$\Omega_a^\pm := \{x \in \Omega; a(x) \gtrless 0\}, \quad \Gamma_b^\pm := \{\rho \in \partial\Omega; b(\rho) \gtrless 0\}.$$

We study now the sign-sets associated to J .

Lemma 6.6. (1) $\mathcal{E}^+ \neq \emptyset$.

(2) If $\Omega_a^+ \neq \emptyset$ then $\mathcal{N}^+ \cap \mathcal{E}^+ \neq \emptyset$.

(3) If $\Gamma_b^+ \neq \emptyset$ then $\mathcal{N}^- \cap \mathcal{E}^+ \neq \emptyset$.

(4) If $\Omega_a^- \neq \emptyset$ and $\Gamma_b^- \neq \emptyset$ then $\mathcal{N}^+ \cap \mathcal{A}^- \neq \emptyset$ and $\mathcal{N}^- \cap \mathcal{B}^- \neq \emptyset$.

Proof. (2) We can easily construct a $C^\infty \cap W_0^{1,p}(\Omega)$ function ξ with support on a small ball where $a > 0$ such that $E(\xi) > 0$.

(3) Let $v \in C^\infty$ be a function defined in $\partial\Omega$ such that $B(v) > 0$ and let $u \in W^{1,p}(\Omega)$ having v as its trace. Let ξ be a C^∞ cut function such that $0 \leq \xi \leq 1$, $\xi \equiv 1$ in a small ball $B(x_0, r) \subset \Omega$ where $|u| > c$ for some $c > 0$, $\xi \equiv 1$ in a neighbourhood $\Omega_\delta := \{x \in \bar{\Omega}; \text{dist}(x, \partial\Omega) < \delta\}$ of $\partial\Omega$, and $\xi = 0$ in $\Omega \setminus (B(x, 2r) \cup \Omega_{2\delta})$. We can assume that

$$c^p \int_{B(x_0, 2r)} |\nabla \xi|^p \geq \int_{B(x_0, 2r)} |\xi|^p (|\nabla u|^p - V|u|^p)$$

which implies that $E(\xi u) > 0$. Thus $\xi u \in \mathcal{B}^+ \cap \mathcal{E}^+$ and from Proposition 2.4 (i) we infer that $\mathcal{N}^+ \cap \mathcal{E}^+ \neq \emptyset$.

- (4) We prove that $\Lambda^- \neq \emptyset$. Let $0 \leq v \in C^\infty$ be a function defined in $\partial\Omega$ such that $B(v) < 0$ and let $u \in W^{1,p}(\Omega)$ having v as its trace. We can assume that $u \geq 0$ by replacing u by $|u|$ if necessary. If $A(u) \geq 0$ let us take a function $0 \leq w \in W_0^{1,p}(\Omega)$ with support in Ω_a^- such that

$$\int_{\Omega_a^-} aw^r < - \int_{\Omega} au^r$$

which implies that $A(u + w) < 0$. Hence replace u by $u + w$, which also has v as trace. Let ξ be a C^∞ cut function such that $0 \leq \xi \leq 1$, $\xi \equiv 1$ in a small ball $B(x_0, r) \subset \Omega_a^-$ where $|u| > c$ for some $c > 0$, $\xi \equiv 1$ in a neighbourhood $\Omega_\delta := \{x \in \bar{\Omega} ; \text{dist}(x, \partial\Omega) < \delta\}$ of $\partial\Omega$, and $\xi = 0$ in $\Omega \setminus (B(x, 2r) \cup \Omega_{2\delta})$. We can assume that

$$c^p \int_{B(x_0, 2r)} |\nabla \xi|^p \geq \int_{B(x_0, 2r)} |\xi|^p (|\nabla u|^p - V|u|^p)$$

which implies that $E(\xi u) > 0$. The cut function ξ can be chosen to satisfy also

$$A(\xi u) > - \left(\frac{q-p}{q-r} \right) \left(\frac{p-r}{q-r} \right)^{\frac{p-r}{q-p}} \frac{(-E(\xi u))^{\frac{q-r}{q-p}}}{(-B(\xi u))^{\frac{p-r}{q-p}}} = \min_{t>0} m_{\xi u}(t).$$

Thus $\xi u \in \Lambda^-$. The proof of the other case is similar. □

We keep here the same notation for the different coerciveness constants, although they read now as follows

$$j_0(a) := \inf \left\{ \int_{\Omega} |\nabla u|^p + V(x)|u|^p ; \int_{\Omega} a|u|^r = 0, \|u\|_{1,p} = 1 \right\},$$

$$j_0(b) := \inf \left\{ \int_{\Omega} |\nabla u|^p + V(x)|u|^p ; \int_{\partial\Omega} b|u|^q = 0, \|u\|_{1,p} = 1 \right\}.$$

We left to the reader the expressions of μ^\pm in terms of the operators E, A, B . We can now formulate an existence and multiplicity result for Problem II. We generalize some results of [10, 17] where this problem was studied for $V \equiv 0, a \equiv b \equiv 1$.

- Theorem 6.7.** (i) Assume that $\Omega_a^+ \neq \emptyset$ and $\Gamma_b^+ \neq \emptyset$. If either $\lambda_1 > 0$ or $\lambda_1 = 0$ and $\int_{\Omega} a\varphi_1^r < 0, \int_{\partial\Omega} b\varphi_1^q < 0$ then there exists at least two solutions for any $\lambda \in (0, \mu_+^{-1})$.
- (ii) Assume that $\Omega_a^+ \neq \emptyset$. If $\lambda_1 = 0$ and $\int_{\Omega} a\varphi_1^r < 0$ then there exists at least one solution for any $\lambda \in (0, \mu_+^{-1})$.
- (iii) Assume that $\Omega_a^- \neq \emptyset$ and $\Gamma_b^- \neq \emptyset$. If $j_0(a) > 0$ and $j_0(b) > 0$ then there exist at least two solutions in \mathcal{E}^- for any $\lambda \in (0, \mu_-^{-1})$.
- (iv) Assume that $\Omega_a^+ \neq \emptyset$. If $\lambda_1 < 0 < \lambda_2, j_0(a) > 0$ and $\int_{\Omega} a\varphi_1^r < 0$ then there exist at least one solution in \mathcal{E}^+ for any $\lambda \in (0, \mu_+^{-1})$

(v) Assume that $\Omega_a^+ \neq \emptyset$ and $\Gamma_b^+ \neq \emptyset$. If $\lambda_1 < 0 < \lambda_2$, $j_0(a) > 0$, $j_0(b) > 0$, $\int_{\Omega} a\varphi_1^r < 0$, and $\int_{\partial\Omega} b\varphi_1^q < 0$ then there exist at least two solutions in \mathcal{E}^+ for any $\lambda \in (0, \mu_+^{-1})$.

The proof of this theorem comes from Theorem 5.7 and the regularity results quoted in the proof of Theorem 6.2.

Corollary 6.8. Assume that $\Omega_a^{\pm} \neq \emptyset$ and $\Gamma_b^{\pm} \neq \emptyset$. If $\lambda_1 < 0 < \lambda_2$, $j_0(a) > 0$, $j_0(b) > 0$, $\int_{\Omega} a\varphi_1^r < 0$, and $\int_{\partial\Omega} b\varphi_1^q < 0$ then there exists **at least 4 solutions** of Problem II for any $\lambda \in (0, \min\{\mu_+\}^{-1}, \mu_-^{-1})$.

Remark 6.9. In [10, 17] the authors also proved non-existence of solutions for large values of λ . To our knowledge this is an open problem in the non coercive case.

6.3. Existence and multiplicity results for Problem III

Let us now discuss the solvability of

$$\begin{cases} \Delta_p^2 u - c|u|^{p-2}u = \lambda a(x)|u|^{r-2}u + b(x)|u|^{q-2}u & \text{in } \Omega; \\ u = \Delta u = 0 & \text{on } \partial\Omega. \end{cases}$$

The open bounded set $\Omega \subset \mathbb{R}^N$ is assumed here to have a Lipschitz boundary and $a, b, c \in L^\infty(\Omega)$ and $c \in \mathbb{R}$. By a solution of this problem we mean a function $u \in W^{2,p}(\Omega) \cap W_0^{1,p}(\Omega)$ such that

$$\int_{\Omega} |\Delta u|^{p-2} \Delta u \Delta \varphi = \int_{\Omega} (c|u|^{p-2}u + \lambda a(x)|u|^{r-2}u + b(x)|u|^{q-2}u) \varphi \quad (6.7)$$

holds for all $\varphi \in W^{2,p}(\Omega) \cap W_0^{1,p}(\Omega)$. Here $V, a, b \in L^\infty(\Omega)$ and $1 < r < p < q < p^{**}$, where

$$p^{**} := \frac{pN}{N-2p} \text{ if } p < \frac{N}{2}; \quad p^{**} := +\infty \text{ otherwise,}$$

is the critical Sobolev exponent for $W^{2,p}(\Omega)$. The space $W(\Omega) := W^{2,p}(\Omega) \cap W_0^{1,p}(\Omega)$ endowed with the equivalent norm

$$\|u\|_W := \|\Delta u\|_p$$

is reflexive uniformly convex Banach space. Take $X = W(\Omega)$,

$$\begin{aligned} E(u) &= \int_{\Omega} (|\Delta u|^p - c|u|^p) \, dx, & A(u) \\ &= \lambda \int_{\Omega} a(x)|u|^r \, dx, & B(u) = \int_{\Omega} b(x)|u|^q \, dx, \end{aligned}$$

and the energy functional

$$\begin{aligned} J(u) &= \frac{1}{p} E(u) - \frac{1}{r} A(u) - \frac{1}{q} B(u) \\ &= \frac{1}{p} \int_{\Omega} (|\Delta u|^p - c|u|^p) \, dx - \frac{\lambda}{r} \int_{\Omega} a(x)|u|^r \, dx - \frac{1}{q} \int_{\Omega} b(x)|u|^q \, dx. \end{aligned}$$

It is clear that A, B satisfy (2.1) and hypothesis **(H1)** since the embedding $W(\Omega) \hookrightarrow L^r(\Omega)$ and $W(\Omega) \hookrightarrow L^q(\Omega)$ are compact (because $r, q < p^{**}$). Thus **(H1)**, **(H2)** and **(H3)** hold.

The coerciveness of E depends on the position of c with respect to the first eigenvalue of the following p -bilaplacian problem

$$\begin{cases} \Delta_p^2 u = \mu |u|^{p-1} u & \text{in } \Omega, \\ u = \Delta u = 0 & \text{on } \partial\Omega, \end{cases} \tag{6.8}$$

with weak formulation

$$\int_{\Omega} |\Delta u|^{p-2} \Delta u \Delta \varphi \, dx = \mu \int_{\Omega} |u|^{p-2} u \varphi \, dx \quad \forall \varphi \in W(\Omega).$$

According to [9] there exists $\lambda_1 > 0$ a least eigenvalue of (6.8), and this eigenvalue is principal, isolated and simple. Furthermore it holds

$$\lambda_1 = \inf \left\{ \int_{\Omega} |\Delta u|^p ; u \in W(\Omega), \|u\|_p = 1 \right\}.$$

Let $\varphi_1 > 0$ with $\|\varphi_1\|_p = 1$ be an eigenfunction associated to λ_1 . Denote by

$$\lambda_2 = \inf \{ \lambda > \lambda_1 ; \lambda \text{ solves (6.8)} \}.$$

The fact that $\lambda_2 \in \mathbb{R}$ is an eigenvalue of the Dirichlet p -bilaplacian and the existence of a sequence of eigenvalues is proved for instance in [19]. Finally let us denote

$$\begin{aligned} \Omega_a^{\pm} &:= \{x \in \Omega ; a(x) \geq 0\}, & \Omega_b^{\pm} &:= \{x \in \Omega ; b(x) \geq 0\}, \\ \Omega_{a,0} &:= \{x \in \Omega ; a(x) = 0\}, & \Omega_{b,0} &:= \{x \in \Omega ; b(x) = 0\}. \end{aligned}$$

Lemma 6.10. (1) $\mathcal{E}^+ \neq \emptyset$.

(2) If $\Omega_a^+ \neq \emptyset$ then $\mathcal{N}^+ \cap \mathcal{E}^+ \neq \emptyset$.

(3) If $\Omega_b^+ \neq \emptyset$ then $\mathcal{N}^- \cap \mathcal{E}^+ \neq \emptyset$.

(4) If $\Omega_a^- \cap \Omega_b^- \neq \emptyset$ then $\mathcal{N}^+ \cap \mathcal{A}^- \neq \emptyset$ and $\mathcal{N}^- \cap \mathcal{B}^- \neq \emptyset$.

Proof. (2) We distinguish two cases:

a) $\Omega_a^+ \cap (\Omega_b^- \cup \Omega_{b,0}) \neq \emptyset$. In this case we can construct a $C^\infty \cap W(\Omega)$ function v with support in a small ball $B(x_0, 2r) \subset \Omega_a^+ \cap (\Omega_b^- \cup \Omega_{b,0})$ such that $A(v) > 0 \geq B(v)$. Let ξ be a C^∞ cut function such that $0 \leq \xi \leq 1$, $\xi \equiv 1$ in $B(x_0, r) \subset \Omega$ where $|v| > \epsilon$ for some $\epsilon > 0$, $\xi \equiv 0$ in $\overline{\Omega} \setminus B(x_0, 2r)$. We can assume that

$$\epsilon^p \int_{B(x_0, 2r)} |\Delta \xi|^p \geq \int_{B(x_0, 2r)} |\xi|^p (|\Delta v|^p + c|v|^p) - 2 \int_{\Omega} |\nabla v|^p |\nabla \xi|^p \tag{6.9}$$

which implies that $E(\xi v) > 0$. Thus $\xi v \in \mathcal{A}^+ \cap \mathcal{B}_0^- \cap \mathcal{E}^+$ and from Proposition 2.4 (i) we infer that $\mathcal{N}^+ \cap \mathcal{E}^+ \neq \emptyset$.

b) If $\Omega_a^+ \subset \Omega_b^+$ the construction of v and ξ is analogous to the previous case, starting with $v \in C^\infty \Omega$ such that $A(v), B(v) > 0$ with support in a small ball $B(x_0, 2r) \subset \Omega_a^+$. The cut function ξ can be chosen in such a way that (6.9) is satisfied as well as

$$A(\xi v) < \left(\frac{q-p}{q-r} \right) \left(\frac{p-r}{q-r} \right)^{\frac{p-r}{q-p}} \frac{E(\xi v)^{\frac{q-r}{q-p}}}{B(\xi v)^{\frac{p-r}{q-p}}} = \max_{t>0} m_{\xi v}(t).$$

The proof of the other cases are similar. □

The coerciveness constants are now

$$j_0(a) := \inf \left\{ \int_{\Omega} |\Delta u|^p - c|u|^p ; \int_{\Omega} a|u|^r = 0, \|u\|_W = 1 \right\},$$

$$j_0(b) := \inf \left\{ \int_{\Omega} |\Delta u|^p - c|u|^p ; \int_{\Omega} b|u|^q = 0, \|u\|_W = 1 \right\}$$

and one also has to rewrite the constants μ^{\pm} in terms of the operators E, A, B . By applying Theorem 5.7 we get

- Theorem 6.11.** (i) Assume that $\Omega_a^+ \neq \emptyset$ and $\Omega_b^+ \neq \emptyset$. If either $c < \lambda_1$ or $c = \lambda_1$ and $\int_{\Omega} a\varphi_1^r < 0, \int_{\Omega} b\varphi_1^q < 0$ then there exist at least two solutions for any $\lambda \in (0, \mu_+^{-1})$.
- (ii) Assume that $\Omega_a^+ \neq \emptyset$. If $c = \lambda_1$ and $\int_{\Omega} a\varphi_1^r < 0$ then there exists at least one solution for any $\lambda \in (0, \mu_+^{-1})$.
- (iii) Assume that $\Omega_a^- \cap \Omega_b^- \neq \emptyset$. If $j_0(a) > 0$ and $j_0(b) > 0$ then there exist at least two solutions in \mathcal{E}^- for any $\lambda \in (0, \mu_-^{-1})$.
- (iv) Assume that $\Omega_a^+ \neq \emptyset$. If $\lambda_1 < c < \lambda_2, j_0(a) > 0$ and $\int_{\Omega} a\varphi_1^r < 0$ then there exists at least one solution in \mathcal{E}^+ for any $\lambda \in (0, \mu_+^{-1})$.
- (v) Assume that $\Omega_a^+ \neq \emptyset$ and $\Omega_b^+ \neq \emptyset$. If $\lambda_1 < c < \lambda_2, j_0(a) > 0, j_0(b) > 0, \int_{\Omega} a\varphi_1^r < 0,$ and $\int_{\Omega} b\varphi_1^q < 0$ then there exist at least two solutions in \mathcal{E}^+ for any $\lambda \in (0, \mu_+^{-1})$.

Corollary 6.12. Assume that $\Omega_a^+ \neq \emptyset, \Omega_b^+ \neq \emptyset$ and $\Omega_a^- \cap \Omega_b^- \neq \emptyset$. If $\lambda_1 < c < \lambda_2, j_0(a) > 0, j_0(b) > 0, \int_{\Omega} a\varphi_1^r < 0,$ and $\int_{\Omega} b\varphi_1^q < 0$ then there exist at least 4 solutions for all $\lambda \in (0, \min\{\mu_+^{-1}, \mu_-^{-1}\})$.

Remark 6.13. Notice that we do not claim in the statement of Theorem 6.11 that the solutions are positive. The reason is that we can not use, for a local minimizer $u \in W^{2,p}(\Omega)$, the relation $J(u) = J(|u|)$ to deduce positivity of solution, since it can happen that $|u| \notin W^{2,p}(\Omega)$ even if $u \in W^{2,p}(\Omega)$. The existence of positive solutions of Problem III is, to our knowledge, an open problem.

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